

On the interval Cholesky method

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Outline

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1. Introduction

Given: $[A] = [A]^T = ([a]_{ij}) \in \mathbb{R}^{n \times n}$ **regular**, $[b] = ([b]_i) \in \mathbb{R}^n$

Enclose the **symmetric solution set**

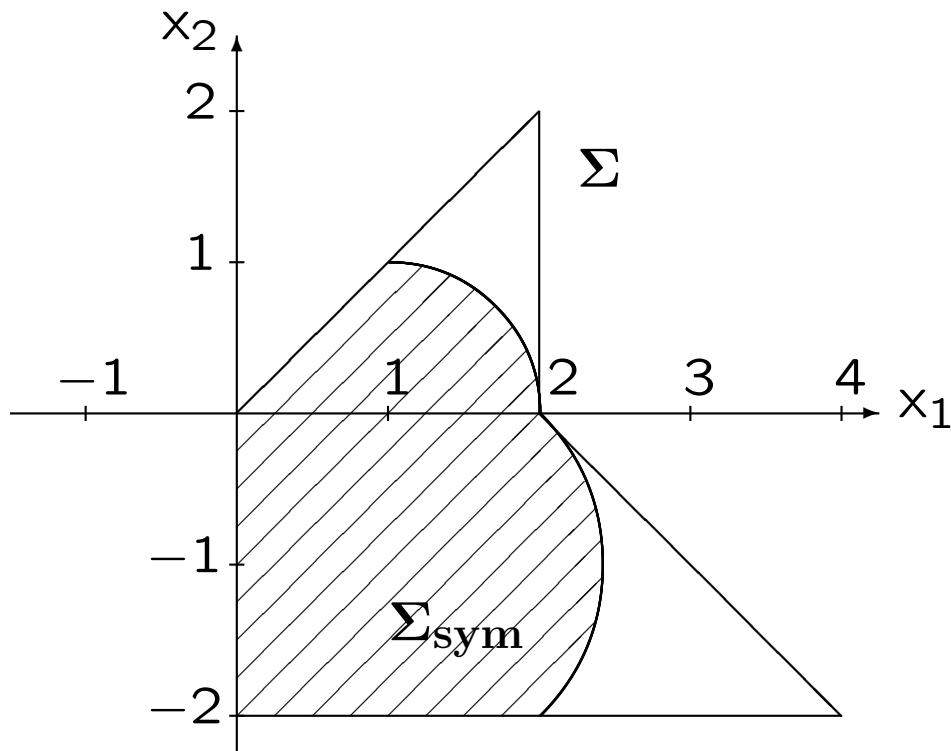
$$\Sigma_{\text{sym}} := \{x \in \mathbb{R}^n \mid Ax = b, A = A^T \in [A] = [A]^T, b \in [b]\}$$

More frequently: Enclose the **solution set**

$$\Sigma := \{x \in \mathbb{R}^n \mid Ax = b, A \in [A], b \in [b]\}$$

Example 1

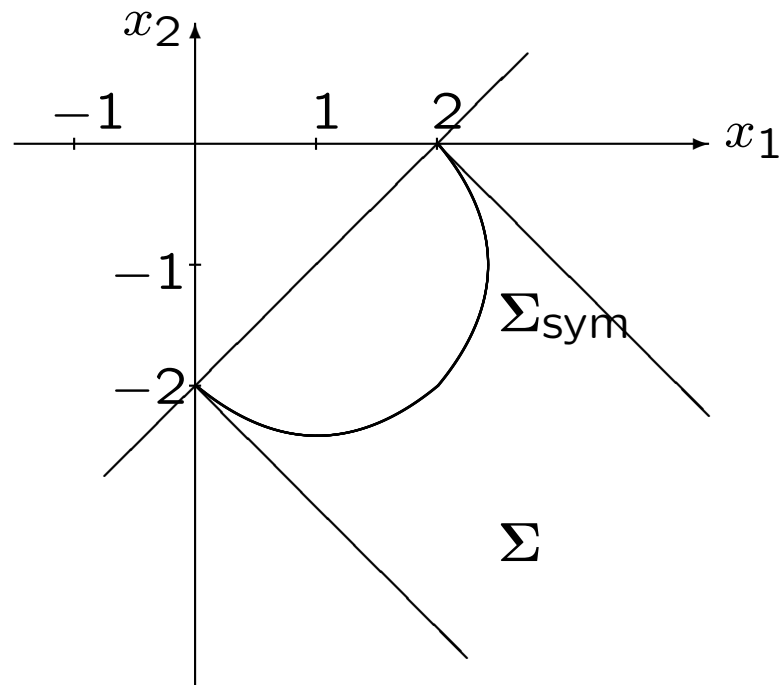
$$[A] = \begin{pmatrix} 1 & [0, 1] \\ [0, 1] & [-4, -1] \end{pmatrix}, \quad [b] = \begin{pmatrix} [0, 2] \\ [0, 2] \end{pmatrix}.$$



Example 2

$$[A] = \begin{pmatrix} 1 & [-1, 1] \\ [-1, 1] & -1 \end{pmatrix}, \quad [b] = \begin{pmatrix} 2 \\ 2 \end{pmatrix}.$$

$[A]$ contains two sing. matrices but **no sing. symmetric** matrix.



$[-1, 1] \rightsquigarrow [-1 + \varepsilon, 1 - \varepsilon]$: **Arbitrarily large overestimation!**

Thus the hull inverse is not adapted to the optimal treatment of symmetric matrices.

However, at present, no special methods have been devised for this case, and we shall content ourselves with the unsymmetric treatment of symmetric matrices.

Neumaier, Interval Methods for Systems of Equations, 1990, p. 95.

Unless you are able to handle dependent data, you will never get interest of the engineers.

Babuška, conversation with J. Rohn, 1992.

Publications on Σ_{sym} (Cholesky method highlighted)

Neumaier	1985, Dec. 23, letter to Rohn 1990
Rohn	1986 (talk 1990; published 2004)
Jansson	1990 (talk; published 1991)
Alefeld / M.	1993, 1995, 2008
Rump	1994
Alefeld / Kreinovich / M.	1995, 1996, 1997, 1998, 2001, 2003
M.	2001, 2007
Schäfer	2001
Hladík	2007, 2008
Popova	2002, 2004, 2007
Popova / Krämer	2007, 2008
Sharaya / Shary	2008

2. Interval Cholesky method (Alefeld/M. 1993, 1995, 2008)

1. LL^T decomposition

for $j := 1$ **to** n **do**

$$[l]_{jj} := ([a]_{jj} - \sum_{k=1}^{j-1} [l]_{jk}^2)^{1/2}$$

for $i := j + 1$ **to** n **do**

$$[l]_{ij} := ([a]_{ij} - \sum_{k=1}^{j-1} [l]_{ik}[l]_{jk}) / [l]_{jj}$$

2. Forward substitution

for $i := 1$ **to** n **do**

$$[y]_i := ([b]_i - \sum_{j=1}^{i-1} [l]_{ij}[y]_j) / [l]_{ii}$$

3. Backward substitution

for $i := n$ **downto** 1 **do**

$$[x]_i^C := ([y]_i - \sum_{j=i+1}^n [l]_{ji}[x]_j^C) / [l]_{ii}$$

Representation of $[x]^C = \text{ICh}([A], [b]) \supseteq \Sigma_{\text{sym}}$

a) Standard formulae

b) Multiple product

$$[x]^C = [D]^{(1)}([L]^{(1)T}([D]^{(2)}([L]^{(2)T}(\dots([L]^{(n-1)T}([D]^{(n)}([D]^{(n)}([L]^{(n-1)}([D]^{(n-1)}(\dots([L]^{(1)}([D]^{(1)}[b]))\dots))\dots))\dots))\dots)$$

c) Recurrence

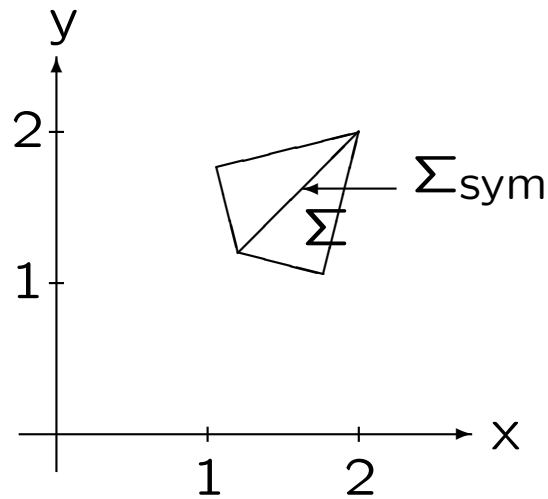
$$[A] = \begin{pmatrix} [a]_{11} & [c]^T \\ [c] & [A]' \end{pmatrix} \quad \text{with } [c] \in \mathbb{R}^{n-1}.$$

The Cholesky decomposition $([L], [L]^T)$ of $[A]$ exists, if $0 < a_{11}$ and if either $n = 1$, $[L] := (\sqrt{[a]_{11}})$, or $n > 1$ and the Cholesky decomposition $([L]', [L]'^T)$ of $[A]' - \frac{1}{[a]_{11}}[c][c]^T$ exists. Then

$$[L] := \begin{pmatrix} \sqrt{[a]_{11}} & 0 \\ [c]/\sqrt{[a]_{11}} & [L]' \end{pmatrix}; \quad [x]^C \text{ as in a) .}$$

Example 3 ($[A]$ H -matrix)

$$[A] := \begin{pmatrix} 4 & [-1, 1] \\ [-1, 1] & 4 \end{pmatrix}, \quad [b] := \begin{pmatrix} 6 \\ 6 \end{pmatrix}$$



$$\begin{aligned} \square \Sigma_{\text{sym}} &\neq \square \Sigma \\ \square \Sigma_{\text{sym}} &\neq [x]^C \\ \square \Sigma &\neq [x]^G \\ \Sigma &\not\subseteq [x]^C \\ [x]^C &\not\subseteq [x]^G \end{aligned}$$

3. Known Results (Alefeld/M. 1993)

Theorem 1

If $[A] \in \mathbb{IR}^{n \times n}$ is an H -matrix with $[A] = [A]^T$ and $0 < \underline{a}_{ii}$ for $i = 1, \dots, n$, then $[x]^C$ exists.

Theorem 2

Let $[A] = [A]^T \in \mathbb{IR}^{n \times n}$ be tridiagonal and let there exist a symmetric positive definite matrix $\tilde{A} \in [A]$ with $\langle \tilde{A} \rangle = \langle [A] \rangle$. Then $[x]^C$ exists.

Theorem 3 (Quality of enclosure)

Let $[A] = [A]^T \in \mathbb{IR}^{n \times n}$ be an M -matrix and let $[b] \in \mathbb{IR}^n$ satisfy $\underline{b} \geq 0$ or $0 \in [b]$ or $\bar{b} \leq 0$.

Then $[x]^C = \square_{\Sigma_{\text{sym}}} = \square_{\Sigma} = [x]^G$.

4. New Results (Alefeld/M. 2008)

Theorem 4

Let $[A] = [A]^T \in \mathbb{IR}^{n \times n}$ contain a symmetric positive definite matrix. If $[x]^G$ exists then $[x]^C$ exists.

Theorem 5

Let $[A] = [A]^T \in \mathbb{IR}^{n \times n}$. If all symmetric matrices in $[A]$ are positive definite – in particular, if $[x]^C$ exists – then x^G exists for each matrix $\tilde{A} \in [A]$.

Theorem 6

Let $[A] = [A]^T \in \mathbb{IR}^{n \times n}$ contain a symmetric and positive definite matrix \tilde{A} and let $n \leq 3$. Then $[x]^C$ exists if and only if $[x]^G$ exists.

The converse of Theorem 4 does not hold!

Example 4 (Counterexample)

Let $[A] = \begin{pmatrix} 1 & [-1, 1] & 0 & 0 \\ [-1, 1] & 2 & 1 & 2 \\ 0 & 1 & 2 & 2 \\ 0 & 2 & 2 & 16/3 \end{pmatrix}$. Then $[x]^C$ exists since

$$[L] = \begin{pmatrix} 1 & 0 & 0 & 0 \\ [-1, 1] & [1, \sqrt{2}] & 0 & 0 \\ 0 & [1/\sqrt{2}, 1] & [1, \sqrt{3/2}] & 0 \\ 0 & [2/\sqrt{2}, 2] & [0, 1] & [\sqrt{1/3}, \sqrt{10/3}] \end{pmatrix},$$

while $[x]^G$ does not exist because of

$$[\hat{U}] = \begin{pmatrix} 1 & [-1, 1] & 0 & 0 \\ 0 & [1, 3] & 1 & 2 \\ 0 & 0 & [1, 5/3] & [0, 4/3] \\ 0 & 0 & 0 & [-4/9, 4] \end{pmatrix}.$$

Theorem 7 (For a variant cf. Frommer 2001)

Let $[A] = [A]^T \in \mathbb{IR}^{n \times n}$ contain a symmetric positive definite matrix. If the (undirected) graph of $\langle [A] \rangle$ is a **tree** and if it is **ordered according to the minimum-degree algorithm**, then the following properties are equivalent.

- (i) $[x]^G$ exists.
- (ii) $[x]^C$ exists.
- (iii) Each symmetric matrix in $[A]$ is positive definite.

Example 5

Let

$$[A] = \begin{pmatrix} 2 & 0 & [-1, 1] \\ 0 & 2 & [-1, 1] \\ [-1, 1] & [-1, 1] & 2 \end{pmatrix} .$$

Each symmetric matrix $\tilde{A} \in [A]$ is positive definite, hence $[x]^C$ exists.

Theorem 8

If $[A] = I + [-R, R]$, $O \leq R = R^T$, $0 < a_{ii}$, $i = 1, \dots, n$, then $[x]^C$ exists if and only if $\rho(R) < 1$, hence if and only if $[A]$ is an H -matrix. Thus $[x]^C$ exists if and only if $[x]^G$ exists.

Definition 1

Let $[A] \in \mathbb{IR}^{n \times n}$.

a) Sign matrix $S = (\text{sign}(\text{mid}([a]_{ij})))$.

b) Extended sign matrix S' :

$$S' = S$$

for $k = 1 : (n - 1)$

for $i = (k + 1) : n$

for $j = (k + 1) : n$

if $s'_{ij} == 0$ **then** $s'_{ij} = -s'_{ik}s'_{kk}s'_{kj}$.

Definition 2

- a) $[A] \in \mathbb{R}^{n \times n}$ is **irreducible** if $|[A]|$ is irreducible.
- b) $[A] \in \mathbb{R}^{n \times n}$ is **generalized diagonally dominant** if there is a vector $x > 0$ such that $\langle [A] \rangle x \geq 0$.

Theorem 9

Let $[A] = [A]^T \in \mathbb{R}^{n \times n}$ be **irreducible and generalized diagonally dominant** with $0 < \underline{a}_{ii}$, $i = 1, \dots, n$. Define S' as above. Then $[x]^C$ exists **if and only if** $[x]^G$ exists **if and only if** $[A]$ is generalized irreducibly diagonally dominant or the sign condition

$$s'_{ij} s'_{ik} s'_{kj} = 1$$

holds for some triple (i, j, k) with $k < j < i$.

Example 6

$$[A] = \begin{pmatrix} 4 & 0 & [0, 2] & [-2, 0] \\ 0 & 4 & [0, 2] & [0, 2] \\ [0, 2] & [0, 2] & [6, 9] & [-2, 2] \\ [-2, 0] & [0, 2] & [-2, 2] & [6, 9] \end{pmatrix}$$

is irreducible and diagonally dominant with

$$S = \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 0 \\ -1 & 1 & 0 & 1 \end{pmatrix} \neq S' = \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix}$$

$[x]^C$ exists by Theorem 9 with $(i, j, k) = (4, 3, 2)$.