

# A Differential Inequalities Method for Verified Solution of IVPs for ODEs using Linear Programming for the Search of Tight Bounds

**Dmitry Nadezhin**

Staff engineer

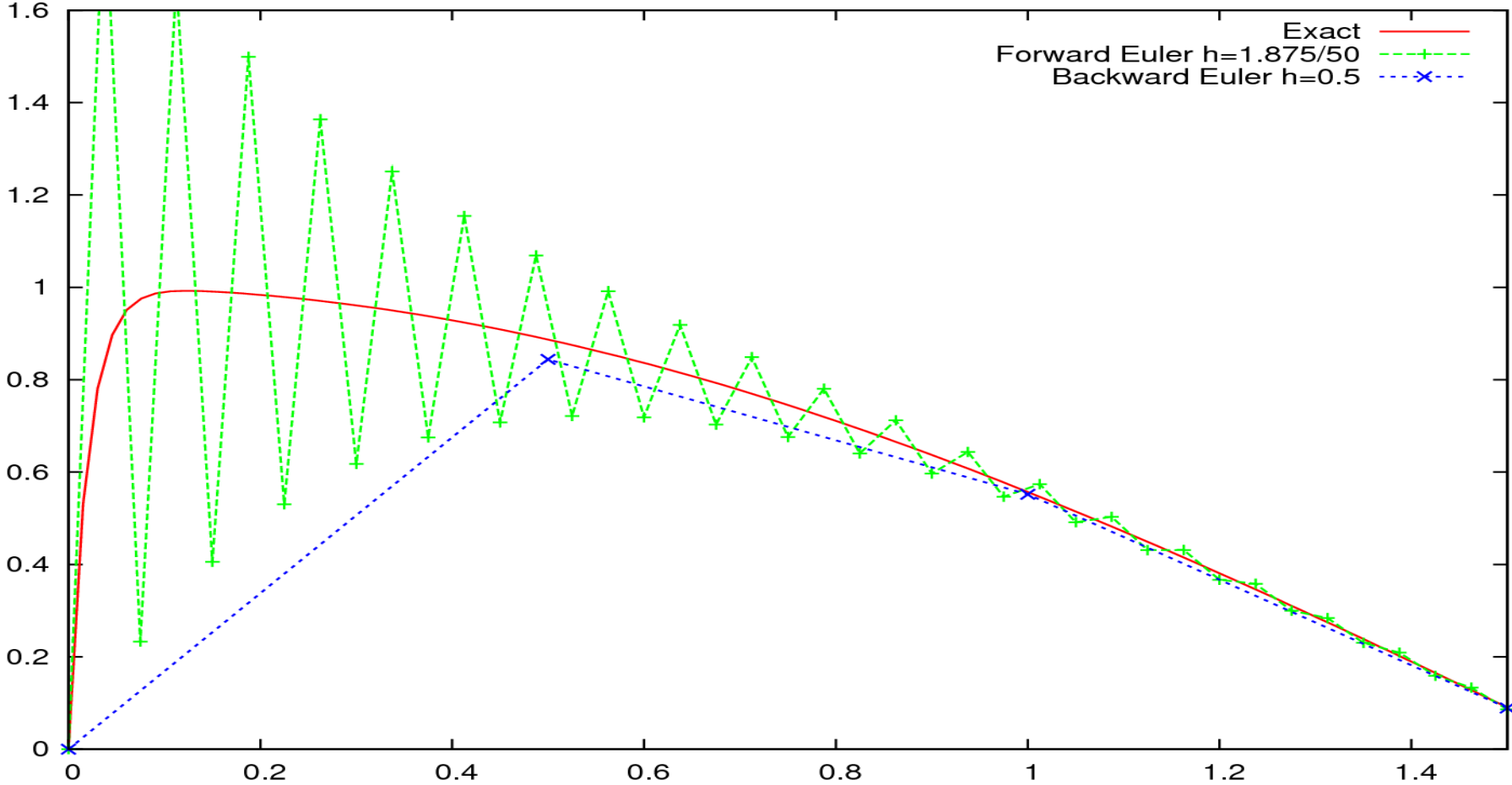
Sun Microsystems

# Stiff IVP Example by Curtiss & Hirschfelder

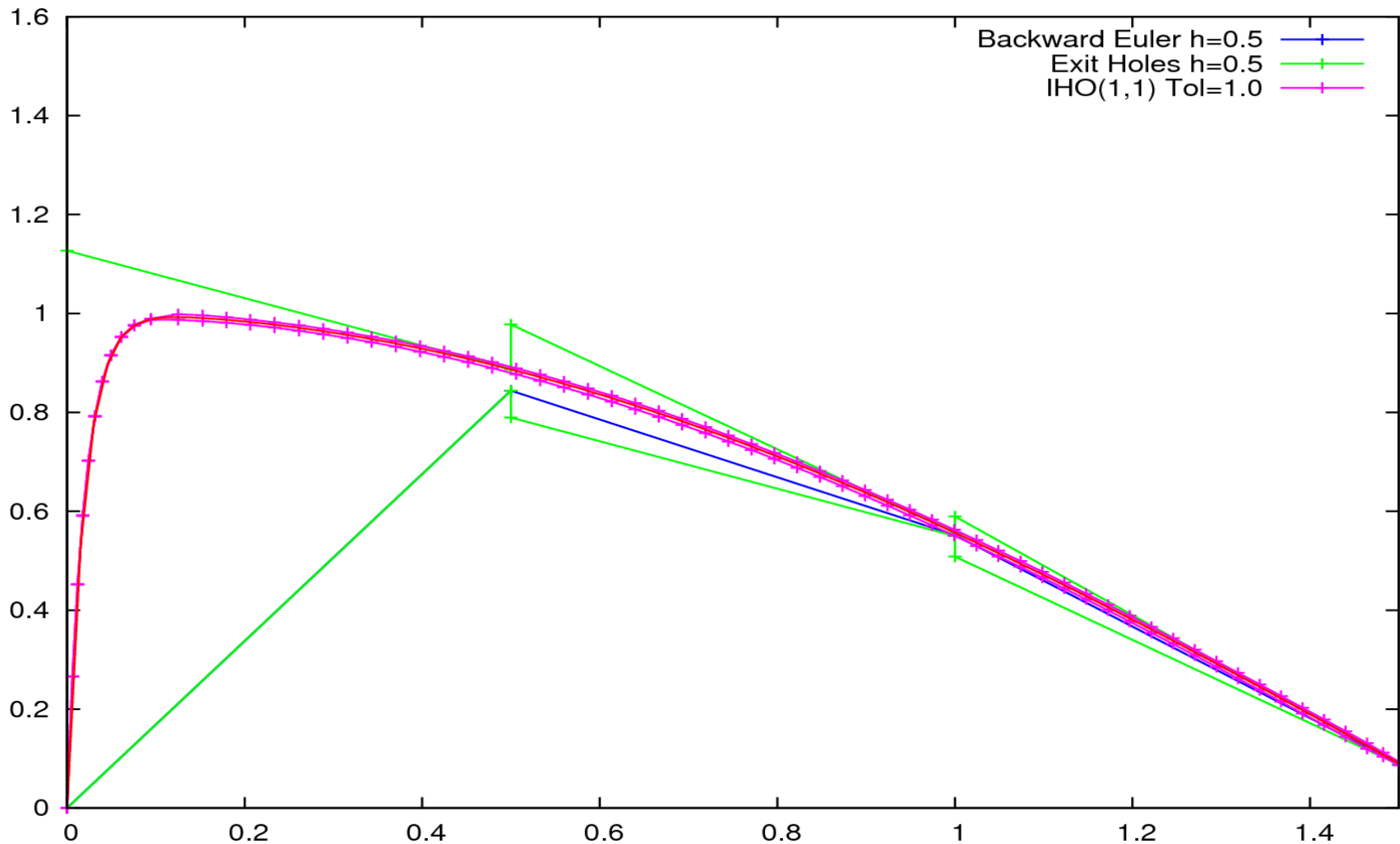
$$\dot{x} = 50 (\cos(t) - x)$$

$$x(0) = 0$$

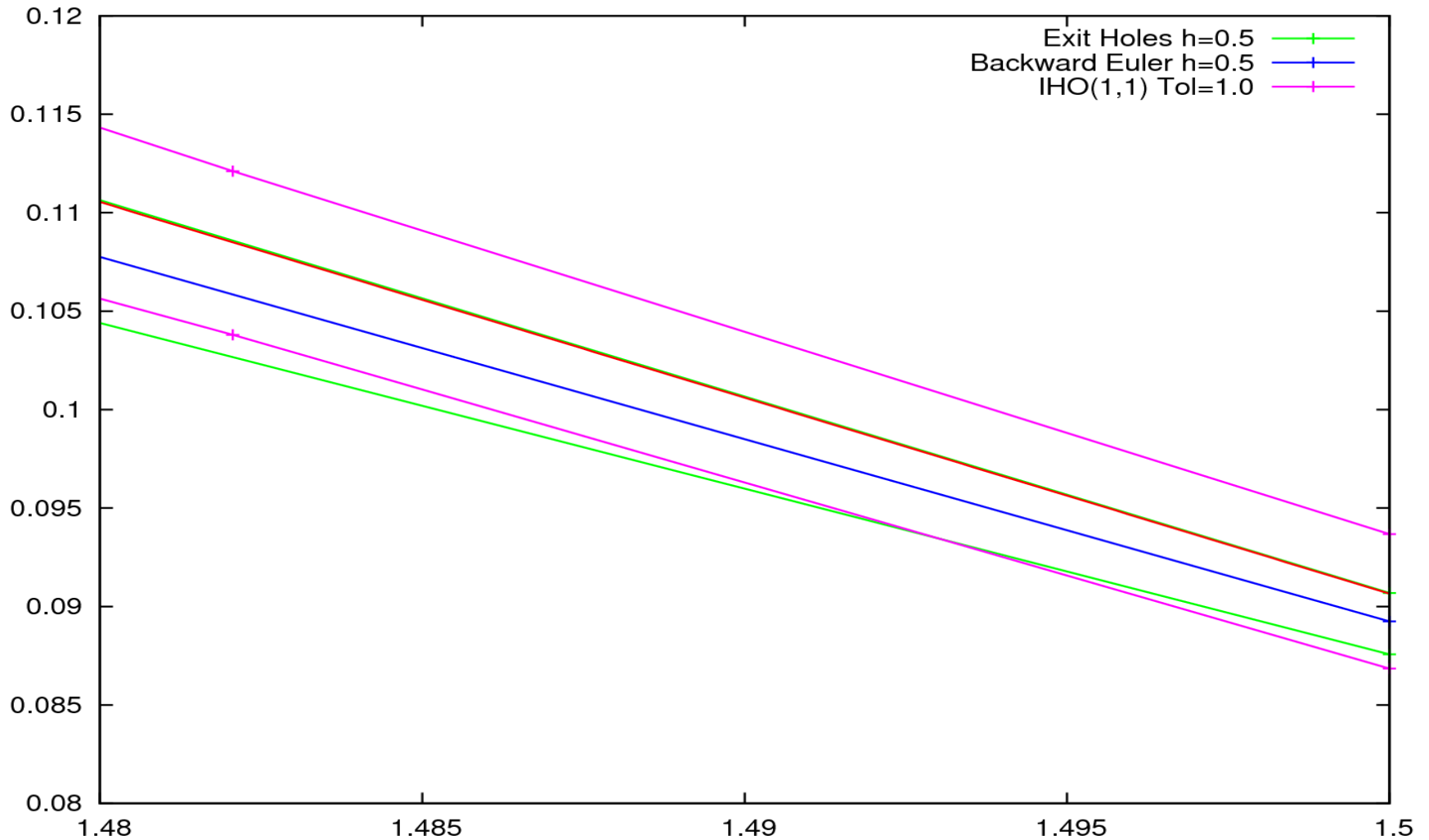
# Forward and Backward Euler Point Solutions of Curtiss & Hirschfelder IVP



# IHO and Exit Holes Interval Solutions of Curtiss & Hirschfelder IVP



# Interval Solutions near the final time

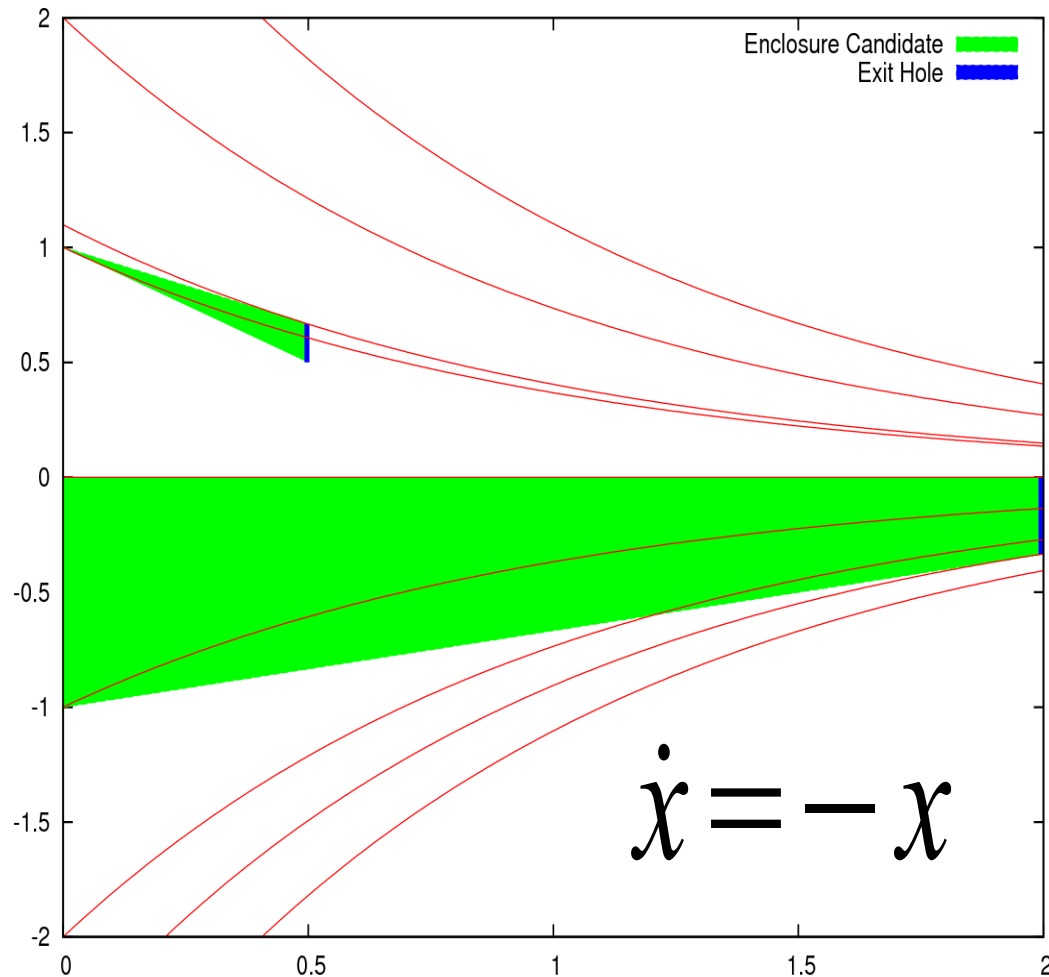


# Works on Interval Solution of IVP

- N. Nedyalkov – Interval Hermite-Obreshkov method
- Kalmykov, Shokin – Chaplygin inequalities
- A. Neumaier – logarithmic norm for realistic bounds of dissipative ODE
- Gennat, Tibken – Muller theorem
- Berz, Makino – Taylor Models

# Exit Hole from Intersection

## Use of Müller Theorem for Scalar Example



# Searching Trapezoid by LP

Search for better Trapezoid using Linear Programming

$$\underline{k}_i \leq F_i(y_c) + \text{HULL}([J^{il}](S^{ilL} - y_c), [J^{il}](S^{ilR} - y_c))$$

- Have an exit hole from the previous step
- Choose time interval
- Guess sufficient large a priori box  $Y_{il}$  and  $Y_{ih}$  for each coordinate (they may be the same), compute  $J$
- Choose the center from point
- Now defect constraint is a convex piecewise linear function
- Optimization target is minimization of hole width



# Searching Trapezoid by LP

## Size of LP problem

$$\underline{k}_i \leq F_i(y_c) + \text{HULL}([J^{il}](S^{ilL} - y_c), [J^{il}](S^{ilR} - y_c))$$

- $4 \cdot n$  variables for  $x$  and  $k$
- $4 \cdot \text{nz}$  variables for interval products for each nonzero Jacobian
- $8 \cdot \text{nz}$  constraints modelling interval products
- $4 \cdot n$  constraints modelling HULL
- $2 \cdot n$  or  $4 \cdot n$  constraints to cover previous exit hole
- Total  $4 \cdot (n + \text{nz})$  variables and  $8 \cdot (n + \text{nz})$  constraints

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Dmitry.Nadezhin@sun.com