

Possibility of Objective Interval Uncertainty in Physics: Analysis

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1. Predictions in Newtonian Physics

- *In Newtonian physics:*
 - once we know the current state of the system,
 - we can predict (at least in principle) all the future states of this system.
- *In real life:*
 - measurements are never absolutely accurate, so we do not have the exact knowledge of the current state.
- *However:*
 - the more accurate our measurements of the current state, the more accurate predictions we can make.
- *The inaccuracy*
 - of the existing knowledge and
 - of the resulting predictions
- can often be described in terms of interval uncertainty.

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2. Predictions in Quantum Physics

- *In quantum physics:*
 - we cannot predict the exact future state of a system;
 - we can only predict the probabilities of different future states.
- *According to the modern quantum physics:*
 - if we know the exact initial state of the world we can uniquely predict these probabilities.
- *This means:*
 - the more accurate our measurements of the current state, the more accurate predictions of probabilities we can make.
- *In practice:*
 - we can often predict the intervals of possible values of the probability.

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3. Possible of Objective Interval-Valued Probabilities

- *It is reasonable to conjecture that:*
 - for some real-life processes,
 - there is no objective probability.
- *In other words:*
 - for different subsequences,
 - the corresponding frequencies can indeed take different values from a given interval.
- The analysis of such processes is given by Gorban in 2007.
- How can we go beyond frequencies in this analysis?
- *A common sense idea:*
 - if an event has probability 0,
 - then it cannot happen.
- This cannot be literally true since every number has probability 0, and thus, no number is random.

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4. Kolmogorov's Definition of Randomness

- *A common sense idea* (reminder):
 - if an event has probability 0,
 - then it cannot happen.
- *Problem*: this cannot be literally true.
- *Reason*:
 - every number has probability 0, and
 - thus, no number is random.
- *Idea of Kolmogorov and Martin-Löf*: we only require that *definable* events of probability 0 do not happen.
- *Good news*: we get a consistent definition of randomness.
- *Reason*:
 - there are only countably many defining texts;
 - thus countably many definable events,
 - the union of countably many events of probability 0 has probability 0;
 - thus, we indeed have a consistent definition of a random object.

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5. How Can We Define When an Object is Random

- *Randomness under a known probability distribution P* (reminder):
 - an object x is random
 - if its does not belong to any definable event E with $P(E) = 0$.
- *Meaning:* if a (definable) event E has probability 0, then it cannot happen.
- *New situation:*
 - we do not know the probability distribution;
 - we only know a class \mathcal{P} of possible probability distributions.
- *Idea:* if a definable event E is guaranteed to have probability 0 (i.e., $P(E) = 0$ for all possible P) then it cannot happen.
- *Resulting definition:*
 - an object x is random
 - if it does not belong to any definable event E for which $P(E) = 0$ for all $P \in \mathcal{P}$.

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6. Observation and a Surprising Result

- *Observation:*
 - if an object x is random w.r.t. some $P_0 \in \mathcal{P}$,
 - then it is also random w.r.t. \mathcal{P} .
- *Proof:*
 - let E be a definable event for which $P(E) = 0$ for all $P \in \mathcal{P}$;
 - we want to prove that $x \notin E$;
 - since $P(E) = 0$ for all $P \in \mathcal{P}$ and $P_0 \in \mathcal{P}$, in particular, $P_0(E) = 0$;
 - since x is P_0 -random, we have $x \notin E$;
 - the observation is proven.
- *Case:* the class \mathcal{P} is finite: $\mathcal{P} = \{P_1, \dots, P_n\}$.
- *According to observation:* for every i , every P_i -random object is \mathcal{P} -random.
- *Natural expectation:* there are \mathcal{P} -random objects which are not P_i -random.
- *Surprising result:* every \mathcal{P} -random object is random with respect to one of the probability measures P_i .

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7. Proof

- *Formulation of the result* (reminder): every \mathcal{P} -random object is random with respect to one of the probability measures P_i .
- *Proof*: by contradiction:
 - let x be \mathcal{P} -random and not random with respect to all P_i ;
 - by definition, P_i -random means that $x \notin E$ for all definable E with $P_i(E) = 0$;
 - thus, the fact that x is not P_i -random means that there exists an event E_i with $P_i(E_i) = 0$ for which $x \in E_i$;
 - since $x \in E_i$ for all i , the object x belongs to the intersection $E \stackrel{\text{def}}{=} \bigcap_{i=1}^n E_i: x \in E$;
 - since $P_i(E_i) = 0$ and $E \subseteq E_i$, we have $P_i(E) = 0$;
 - thus, x belongs to the event E for which $P_i(E) = 0$ for all i ;
 - this contradicts to our assumption that x is \mathcal{P} -random;
 - the statement is proven.
- *We hope*: that this problem does not appear in the more physical interval-valued class \mathcal{P} .

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8. References

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 - *Comment*: this book promotes the idea of objective interval-valued probabilities.
- (2) Li, M., and Vitányi, P.: *An Introduction to Kolmogorov Complexity and Its Applications*, Springer, Berlin-Heidelberg, 1997.
 - *Comment*: this book provides a general introduction to Kolmogorov complexity and randomness.
- (3) Kreinovich, V., and Longpré, L.; *International Journal on Theoretical Physics*, 1997, Vol. 36, No. 1, pp. 167–176.
 - *Comment*: this paper contains the ideas that we used in our proof.

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