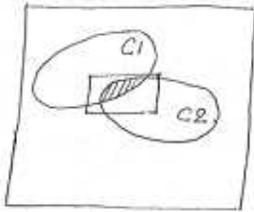


Solving constraints \rightarrow NP hard problem. (using heuristics the time is reduced)



Interval Computations:

\downarrow known relation.

So far: x_1, \dots, x_n ; $y = f(x_1, x_2, \dots, x_n)$

$\tilde{x}_1, \tilde{x}_2, \dots, \tilde{x}_n$ - measurement results

$\tilde{y} = f(\tilde{x}_1, \tilde{x}_2, \dots, \tilde{x}_n)$ - result of data processing

We know:

$$\Delta x_i = \tilde{x}_i - x_i \neq 0$$

So far: assuming that $\Delta x_1, \dots, \Delta x_n$ are normally distributed, w/o mean and SD is σ_i (known)

Δy ? \rightarrow normally distributed, w/o mean and st. dev.

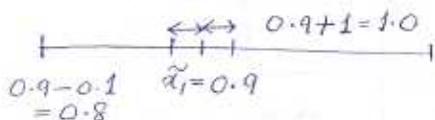
$$\sigma = \sqrt{\sum_{i=1}^n \left(\frac{\partial f}{\partial x_i}\right)^2 \sigma_i^2}$$

In practice, often we don't know the distribution; all we know is upper bound on measurement error.

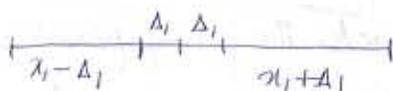
$$\Delta_1, \dots, \Delta_n \quad |\Delta x_i| \leq \Delta_i$$

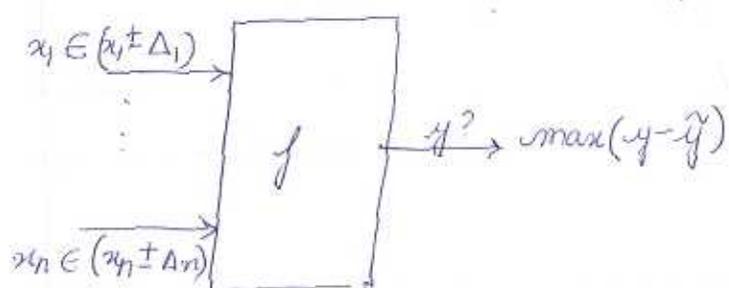
$x_i \in [\tilde{x}_i - \Delta_i, \tilde{x}_i + \Delta_i] \rightarrow$ all we know:

$$\tilde{x}_1 = 0.9, \Delta_1 = 0.1$$



$$[\tilde{x}_1 - \Delta_1, \tilde{x}_1 + \Delta_1]$$





Using Ohm's Law,

$$V = IR$$

$$\tilde{I} = 1.0, \Delta_I = 0.1 \quad I \in [0.9, 1.1]$$

$$\tilde{R} = 2.0, \Delta_R = 0.2 \quad R \in [1.8, 2.2]$$

$$V = 1.2 = 2.0$$

$$V = 0.9 \cdot 2.2 = 1.98$$

$$[V] = [0.9 \cdot 1.8, 1.1 \cdot 2.2] = [1.62, 2.42]$$

$$V = 1.1 \cdot 1.8 = 1.98$$

$$V = 1.05 \cdot 2.02 = 2.1$$

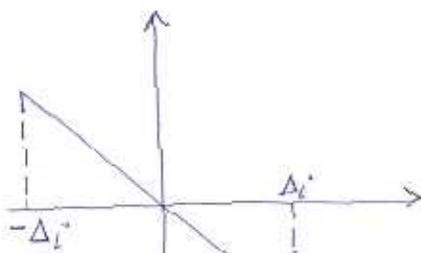
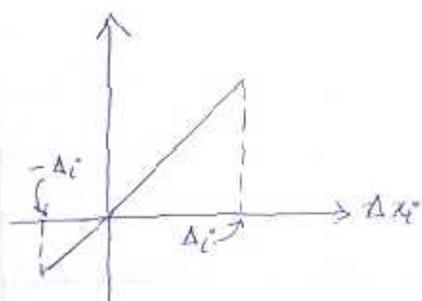
$$\Delta y = \sum_{i=1}^n \frac{\partial f}{\partial x_i} \cdot \Delta x_i$$

$$\Delta x_i \in [-\Delta_i, \Delta_i]$$

when is Δ_i the largest?

inputs: $\Delta_1, \Delta_2, \dots, \Delta_m$

property: Δy is monotonic in each Δx_i



$$\frac{\partial f}{\partial x_i} > 0 \Rightarrow \frac{\partial f}{\partial x_i} \Delta_i$$

$$\frac{\partial f}{\partial x_i} < 0 \Rightarrow \frac{\partial f}{\partial x_i} (-\Delta_i) = \left(-\frac{\partial f}{\partial x_i}\right) \Delta_i$$

$$\left|\frac{\partial f}{\partial x_i}\right|$$

conclusion: $\Delta = \sum_{i=1}^n \left| \frac{\partial f}{\partial x_i} \right| \Delta x_i$

$$\tilde{I} = 1.0, \Delta_I = 0.1$$

$$\tilde{R} = 2.0, \Delta_R = 0.2$$

$$f(I, R) = I \cdot R$$

$$\tilde{x}_1 = 1.0, \Delta_1 = 0.1$$

$$\tilde{x}_2 = 2.0, \Delta_2 = 0.2$$

$$f(x_1, x_2) = x_1 \cdot x_2$$

$$\tilde{y} = 2$$

$$[1.62, 2.42]$$

actual range.

$$\frac{\partial f}{\partial x_1} = x_2 = 2.0$$

$$\frac{\partial f}{\partial x_2} = x_1 = 1.0$$

$$\Delta = |2.0| \cdot 0.1 + |1.0| \cdot 0.2 = 0.4$$

$$y \in [\tilde{y} - \Delta, \tilde{y} + \Delta]$$

$2.0 \quad 0.4$

$$[1.6, 2.4]$$

h/w:

- 1) run a numerical eq of interval computation; compare with linearized range.
- 2) write a code to compute Δ by using numerical diff (by hand) & check by exhaustive search.

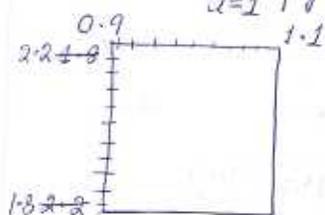
Numerical Differentiation:

$$\frac{\partial f}{\partial x_i} = \frac{f(\tilde{x}_1, \dots, \tilde{x}_{i-1}, \tilde{x}_i + h_i, \tilde{x}_{i+1}, \dots, \tilde{x}_n) - \tilde{y}}{h_i}$$

$$\Delta = \sum_{i=1}^m \left| \frac{f(\tilde{x}_1, \dots, \tilde{x}_{i-1}, \tilde{x}_i + h_i, \tilde{x}_{i+1}, \dots, \tilde{x}_n) - \tilde{y}}{h_i} \right| \Delta_i$$

If we choose to simplify computations, we choose $h_i = \Delta_i$.

$$\Delta = \sum_{i=1}^m \left| f(\tilde{x}_1, \dots, \tilde{x}_{i-1}, \tilde{x}_i + \Delta_i, \tilde{x}_{i+1}, \dots, \tilde{x}_n) - \tilde{y} \right|$$



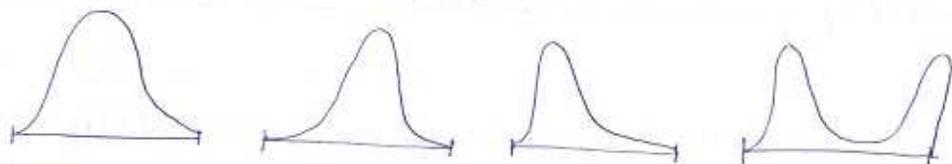
```
for (x1 = x1 - Δ; x1 <= x1 + Δ; x1 += Δ/10)
  for (x2 = ... )
    y = f(x1, x2);
    if (y > y_max) then y_max = y;
```

Problems

① (same as stat.)

when n is large, we have too many calls to f .

② linearization is an approximate tool. (In general linearization - NP-hard)



Ideally: we need \approx Monte Carlo method.

Problem: $\sum_{i=1}^m \frac{\partial f}{\partial x_i} \Delta x_i$

$$\sigma^2 = \sqrt{\sum \left(\frac{\partial f}{\partial x_i}\right)^2 \alpha_i^2}$$

Example: $f(x_1, x_2, \dots, x_n) = \Delta x_1 + \Delta x_2 + \dots + \Delta x_n$

$$|\Delta x_i| \leq \Delta x_i = \Delta_1 = \Delta_2 = \Delta_3 \dots = \Delta_m$$

correct answer: $m \cdot \Delta_1$

$$f(x_1, x_2, \dots, x_n) = x_1 + x_2 + \dots + x_n$$

$$\tilde{y} = \tilde{x}_1 + \tilde{x}_2 + \dots + \tilde{x}_n$$

$$\Delta y = \tilde{y} - y = (\tilde{x}_1 + \tilde{x}_2 + \dots + \tilde{x}_n) - (x_1 + x_2 + \dots + x_n)$$

$$= \tilde{x}_1 + \tilde{x}_2 + \dots + \tilde{x}_n - x_1 - x_2 - \dots - x_n$$

$$= (\tilde{x}_1 - x_1) + (\tilde{x}_2 - x_2) + \dots + (\tilde{x}_n - x_n)$$

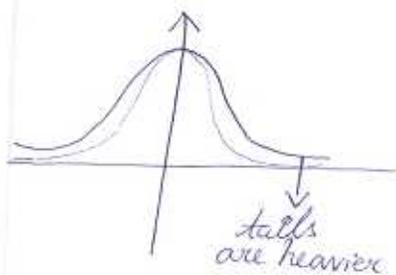
$$= \Delta x_1 + \Delta x_2 + \dots + \Delta x_n$$

$$\Delta y = \sum \frac{\partial f}{\partial x_i} \Delta x_i$$

$$\therefore \sqrt{\sum \alpha_i^2} \leq \sqrt{m \cdot \Delta_i^2} = \Delta_i \sqrt{m} \quad \left[\text{From } \sigma^2 = \sum \left(\frac{\partial f}{\partial x_i}\right)^2 \alpha_i^2 \right]$$

$$\alpha_i^2 \leq \Delta_i^2$$

Cauchy Distribution:

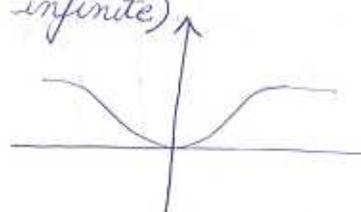


$$p(x) = \frac{\Delta}{\pi} \frac{1}{1+(x/\Delta)^2}$$

$$p_{\text{Gauss}}(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{x^2}{2\sigma^2}\right) \quad x=3\sigma$$

In Gaussian distribution; the tails go to 0. In Cauchy's dis; tails are infinite, they never go to 0. (variance is infinite)

$$V = \sum p_i x_i^2 = \int_{-\infty}^{\infty} p(x) \cdot x^2 dx = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{x^2}{(1+x^2)} dx.$$



Gaussian Distribution:

$$\Delta y = \sum_{i=1}^m c_i \Delta x_i$$

Δx_i are Gaussian st dev σ_i then Δy is also Gaussian w/st dev

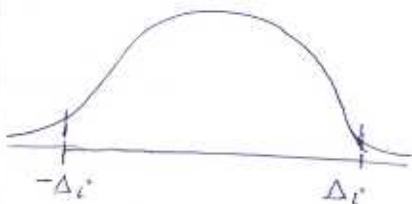
$$\sigma = \sqrt{\sum_{i=1}^m c_i \sigma_i^2}$$

Cauchy Distribution:

$$\Delta y = \sum c_i \Delta x_i$$

Δx_i are Cauchy w/ param Δ_i then Δy is also Cauchy distrib with param Δ

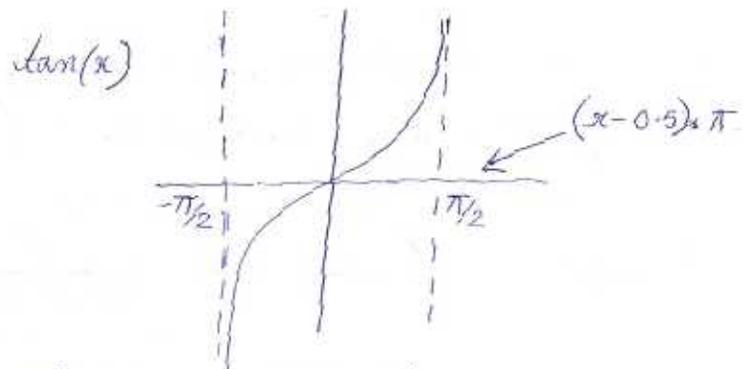
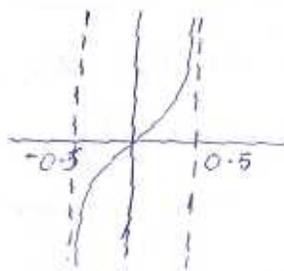
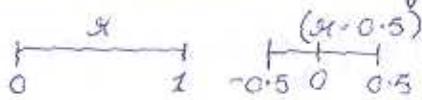
$$\Delta = \sum_{i=1}^m |c_i| \Delta_i$$



2 questions:

- 1) How to simulate Cauchy Distribution?
- 2) How to estimate Δ , based on sample.

How to Simulate Cauchy Distribution:



$$c = \tan\left(\left(\text{rand}() - 0.5\right) * \left(\text{Math.PI} / 2\right)\right)$$

$$p(x) \cdot \Delta x$$

Cauchy Distribution with delta:

$$c = \text{Delta} * \tan\left(\left(\text{rand}() - 0.5\right) * \left(\text{Math.PI}\right)\right)$$