How Physics Can Influence What Is Computable: Taking Into Account that We Process Physical Data and that We Can Use Non-Standard Physical Phenomena to Process This Data

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1. Computations with Real Numbers: Reminder

- \bullet From the physical viewpoint, real numbers x describe values of different quantities.
- We get values of real numbers by measurements.
- Measurements are never 100% accurate, so after a measurement, we get an approximate value r_k of x.
- \bullet In principle, we can measure x with higher and higher accuracy.
- So, from the computational viewpoint, a real number is a sequence of rational numbers r_k for which, e.g.,

$$|x - r_k| \le 2^{-k}.$$

- By an algorithm processing real numbers, we mean an algorithm using r_k as an "oracle" (subroutine).
- This is how computations with real numbers are defined in *computable analysis*.

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- No algorithm is possible that, given two numbers x and y, would check whether x = y.
- Similarly, we can define a computable function f(x) from real numbers to real numbers as a mapping that:
 - given an integer n, a rational number x_m and its accuracy 2^{-m} ,
 - produces y_n which is 2^{-n} -close to all values f(x) with $d(x, x_m) \leq 2^{-m}$ (or nothing)

so that for every x and for each desired accuracy n, there is an m for which a y_n is produced.

- We can similarly define a computable function f(x) on a computable compact set K.
- No algorithm is possible that, given f, returns x s.t. $f(x) = \max_{y \in K} f(y)$. (The max itself is computable.)



3. From the Physicists' Viewpoint, These Negative Results Seem Rather Theoretical

- In mathematics, if two numbers coincide up to 13 digits, they may still turn to be different.
- For example, they may be 1 and $1 + 10^{-100}$.
- In physics, if two quantities coincide up to a very high accuracy, it is a good indication that they are equal:
 - if an experimentally value is very close to the theoretical prediction,
 - this means that this theory is (triumphantly) true.
- This is how General Relativity was confirmed.
- This is how physicists realized that light is formed of electromagnetic waves: their speeds are very close.



4. How Physicists Argue

- In math, if two numbers coincide up to 13 digits, they may still turn to be different: e.g., 1 and $1 + 10^{-100}$.
- In physics, if two quantities coincide up to a very high accuracy, it is a good indication that they are equal.
- A typical physicist argument is that:
 - while numbers like $1 + 10^{-100}$ (or $c \cdot (1 + 10^{-100})$) are, in principle, possible,
 - they are abnormal (not typical).
- In physics, second order terms like $a \cdot \Delta x^2$ of the Taylor series can be ignored if Δx is small, since:
 - while abnormally high values of a (e.g., $a = 10^{40}$) are mathematically possible,
 - typical (= not abnormal) values appearing in physical equations are usually of reasonable size.



5. How to Formalize the Physicist's Intuition of Physically Meaningful Values: Main Idea

- To some physicist, all the values of a coefficient a above 10 are abnormal.
- To another one, who is more cautious, all the values above 10 000 are abnormal.
- For every physicist, there is a value n such that all value above n are abnormal.
- This argument can be generalized as a following property of the set \mathcal{T} of all physically meaningful elements.
- Suppose that we have a monotonically decreasing sequence of sets $A_1 \supseteq A_2 \supseteq \ldots$ for which $\bigcap_n A_n = \emptyset$.
- In the above example, A_n is the set of all numbers $\geq n$.
- Then, there exists an integer N for which $\mathcal{T} \cap A_N = \emptyset$.

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6. How to Formalize the Physicist's Intuition: Resulting Definition

- **Definition.** We thus say that \mathcal{T} is a set of physically meaningful elements if:
 - for every definable decreasing sequence $\{A_n\}$ for which $\bigcap_n A_n = \emptyset$,
 - there exists an N for which $\mathcal{T} \cap A_N = \emptyset$.
- \bullet Comment. Of course, to make this definition precise,
 - we must restrict definability to a *subset* of properties.
 - so that the resulting notion of definability will be defined in ZFC itself.

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- *Known:* equality of real numbers is undecidable.
- For physically meaningful real numbers, however, a deciding algorithm *is* possible:
 - for every set $\mathcal{T} \subseteq \mathbb{R}^2$ which consists of physically meaningful pairs (x, y) of real numbers,
 - there exists an algorithm deciding whether x = y.
- Proof: We can take $A_n = \{(x,y) : 0 < |x-y| < 2^{-n}\}$. The intersection of all these sets is empty.
- Hence, \mathcal{T} has no elements from $\bigcap_{n=1}^{N_A} A_n = A_{N_A}$.
- Thus, for each $(x, y) \in \mathcal{T}$, x = y or $|x y| \ge 2^{-N_A}$.
- We can detect this by taking $2^{-(N_A+3)}$ -approximations x' and y' to x and y. Q.E.D.

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8. Finding Roots

- In general, it is not possible, given a f-n f(x) attaining negative and positive values, to compute its root.
- This becomes possible if we restrict ourselves to physically meaningful functions:
- Let K be a computable compact.
- Let X be the set of all functions $f: K \to \mathbb{R}$ that attain 0 value somewhere on K. Then:
 - for every set $\mathcal{T} \subseteq X$ consisting of physically meaningful functions and for every $\varepsilon > 0$,
 - there is an algorithm that, given a f-n $f \in \mathcal{T}$, computes an ε -approximation to the set of roots

$$R \stackrel{\text{def}}{=} \{x : f(x) = 0\}.$$

• In particular, we can compute an ε -approximation to one of the roots.



9. Optimization

- In general, it is not algorithmically possible to find x where f(x) attains maximum.
- Let K be a computable compact. Let X be the set of all functions $f: K \to \mathbb{R}$. Then:
 - for every set $\mathcal{T} \subseteq X$ consisting of physically meaningful functions and for every $\varepsilon > 0$,
 - there is an algorithm that, given a f-n $f \in \mathcal{T}$, computes an ε -approx. to $S = \left\{ x : f(x) = \max_{y} f(y) \right\}$.
- In particular, we can compute an approximation to an individual $x \in S$.
- Reduction to roots: $f(x) = \max_{y} f(y)$ iff g(x) = 0, where $g(x) \stackrel{\text{def}}{=} f(x) - \max_{y} f(y)$.



10. Computing Fixed Points

- In general, it is not possible to compute all the fixed points of a given computable function f(x).
- Let K be a computable compact. Let X be the set of all functions $f: K \to K$. Then:
 - for every set $\mathcal{T} \subseteq X$ consisting of physically meaningful functions and for every $\varepsilon > 0$,
 - there is an algorithm that, given a f-n $f \in \mathcal{T}$, computes an ε -approximation to the set $\{x : f(x) = x\}$.
- In particular, we can compute an approximation to an individual fixed point.
- Reduction to roots: f(x) = x iff g(x) = 0, where $g(x) \stackrel{\text{def}}{=} d(f(x), x)$.



11. Computing Limits

- In general: it is not algorithmically possible to find a limit $\lim a_n$ of a convergent computable sequence.
- Let K be a computable compact. Let X be the set of all convergent sequences $a = \{a_n\}, a_n \in K$. Then:
 - for every set $\mathcal{T} \subseteq X$ consisting of physically meaningful functions and for every $\varepsilon > 0$,
 - there exists an algorithm that, given a sequence $a \in \mathcal{T}$, computes its limit with accuracy ε .
- *Use:* this enables us to compute limits of iterations and sums of Taylor series (frequent in physics).
- Main idea: for every $\varepsilon > 0$ there exists $\delta > 0$ such that when $|a_n a_{n-1}| \le \delta$, then $|a_n \lim a_n| \le \varepsilon$.
- *Intuitively:* we stop when two consequent iterations are close to each other.



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12. Solving NP-Complete Problems Is Important

- In practice, we often need to find a solution that satisfies a given set of constraints.
- At a minimum, we need to check whether such a solution is possible.
- Once we have a candidate, we can feasibly check whether this candidate satisfies all the constraints.
- In theoretical computer science, "feasibly" is usually interpreted as computable in polynomial time.
- The class of all such problems is called NP.
- Example: satisfiability checking whether a formula like $(v_1 \lor \neg v_2 \lor v_3) \& (v_4 \lor \neg v_2 \lor \neg v_5) \& \dots$ can be true.
- Each problem from the class NP can be algorithmically solved by trying all possible candidates.



13. NP-Complete Problems (cont-d)

- For example, we can try all 2^n possible combinations of true-or-false values v_1, \ldots, v_n .
- For medium-size inputs, e.g., for $n \approx 300$, the resulting time 2^n is larger than the lifetime of the Universe.
- So, these exhaustive search algorithms are not practically feasible.
- It is not known whether problems from the class NP can be solved feasibly (i.e., in polynomial time).
- This is the famous open problem $P \stackrel{?}{=} NP$.
- We know that some problems are *NP-complete*: every problem from NP can be reduced to it.
- So, it is very important to be able to efficiently solve even one NP-hard problem.



14. Can Non-Standard Physics Speed Up the Solution of NP-Complete Problems?

- NP-complete means difficult to solve on computers based on the usual physical techniques.
- A natural question is: can the use of non-standard physics speed up the solution of these problems?
- This question has been analyzed for several specific physical theories, e.g.:
 - for quantum field theory,
 - for cosmological solutions with wormholes and/or casual anomalies.
- So, a scheme based on a theory may not work.



- In the history of physics,
 - always new observations appear
 - which are not fully consistent with the original theory.
- For example, Newton's physics was replaced by quantum and relativistic theories.
- Many physicists believe that every physical theory is approximate.
- For each theory T, inevitably new observations will surface which require a modification of T.
- Let us analyze how this idea affects computations.

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16. No Physical Theory Is Perfect: How to Formalize This Idea

- Statement: for every theory, eventually there will be observations which violate this theory.
- To formalize this statement, we need to formalize what are *observations* and what is a *theory*.
- Most sensors already produce *observation* in the computer-readable form, as a sequence of 0s and 1s.
- Let ω_i be the bit result of an experiment whose description is i.
- Thus, all past and future observations form a (potentially) infinite sequence $\omega = \omega_1 \omega_2 \dots$ of 0s and 1s.
- A physical *theory* may be very complex.
- All we care about is which sequences of observations ω are consistent with this theory and which are not.

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- So, a physical theory T can be defined as the set of all sequences ω which are consistent with this theory.
- A physical theory must have at least one possible sequence of observations: $T \neq \emptyset$.
- A theory must be described by a finite sequence of symbols: the set T must be definable.
- How can we check that an infinite sequence $\omega = \omega_1 \omega_2 \dots$ is consistent with the theory?
- The only way is check that for every n, the sequence $\omega_1 \dots \omega_n$ is consistent with T; so:

$$\forall n \,\exists \omega^{(n)} \in T \,(\omega_1^{(n)} \ldots \omega_n^{(n)} = \omega_1 \ldots \omega_n) \Rightarrow \omega \in T.$$

• In mathematical terms, this means that T is closed in the Baire metric $d(\omega, \omega') \stackrel{\text{def}}{=} 2^{-N(\omega, \omega')}$, where

$$N(\omega, \omega') \stackrel{\text{def}}{=} \max\{k : \omega_1 \dots \omega_k = \omega'_1 \dots \omega'_k\}.$$

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18. What Is a Physical Theory: Definition

- A theory must predict something new.
- So, for every sequence $\omega_1 \dots \omega_n$ consistent with T, there is a continuation which does not belong to T.
- \bullet In mathematical terms, T is nowhere dense.
- By a physical theory, we mean a non-empty closed nowhere dense definable set T.
- A sequence ω is consistent with the no-perfect-theory principle if it does not belong to any physical theory.
- In precise terms, ω does not belong to the union of all definable closed nowhere dense set.
- There are countably many definable set, so this union is $meager (= Baire first \ category)$.
- Thus, due to Baire Theorem, such sequences ω exist.

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19. How to Represent Instances of an NP-Complete Problem

- For each NP-complete problem \mathcal{P} , its instances are sequences of symbols.
- In the computer, each such sequence is represented as a sequence of 0s and 1s.
- We can append 1 in front and interpret this sequence as a binary code of a natural number i.
- In principle, not all natural numbers i correspond to instances of a problem \mathcal{P} .
- We will denote the set of all natural numbers which correspond to such instances by $S_{\mathcal{P}}$.
- For each $i \in S_{\mathcal{P}}$, we denote the correct answer (true or false) to the *i*-th instance of the problem \mathcal{P} by $s_{\mathcal{P},i}$.



20. What We Mean by Using Physical Observations in Computations

- In addition to performing computations, our computational device can:
 - produce a scheme i for an experiment, and then
 - use the result ω_i of this experiment in future computations.
- In other words, given an integer i, we can produce ω_i .
- In precise terms, the use of physical observations in computations means that use ω as an *oracle*.



21. Main Result

- A ph-algorithm \mathcal{A} is an algorithm that uses an oracle ω consistent with the no-perfect-theory principle.
- The result of applying an algorithm \mathcal{A} using ω to an input i will be denoted by $\mathcal{A}(\omega, i)$.
- We say that a feasible ph-algorithm \mathcal{A} solves almost all instances of an NP-complete problem \mathcal{P} if:

$$\forall \varepsilon_{>0} \, \forall n \, \exists N_{\geq n} \, \left(\frac{\#\{i \leq N : i \in S_{\mathcal{P}} \, \& \, \mathcal{A}(\omega, i) = s_{\mathcal{P}, i}\}}{\#\{i \leq N : i \in S_{\mathcal{P}}\}} > 1 - \varepsilon \right).$$

- Restriction to sufficiently long inputs $N \geq n$ makes sense: for short inputs, we can do exhaustive search.
- Theorem. For every NP-complete problem \mathcal{P} , there is a feasible ph-alg. A solving almost all instances of \mathcal{P} .



- Our result is the best possible, in the sense that the use of physical observations cannot solve *all* instances:
- Proposition. If $P \neq NP$, then no feasible ph-algorithm A can solve all instances of P.
- Can we prove the result for all N starting with some N_0 ?
- We say that a feasible ph-algorithm \mathcal{A} δ -solves \mathcal{P} if

$$\exists N_0 \,\forall N \geq N_0 \, \left(\frac{\#\{i \leq N : i \in S_{\mathcal{P}} \,\&\, \mathcal{A}(\omega, i) = s_{\mathcal{P}, i}\}}{\#\{i \leq N : i \in S_{\mathcal{P}}\}} > \delta \right).$$

- Proposition. For every NP-complete problem \mathcal{P} and for every $\delta > 0$:
 - if there exists a feasible ph-algorithm \mathcal{A} that δ solves \mathcal{P} ,
 - then there is a feasible algorithm \mathcal{A}' that also δ -solves \mathcal{P} .

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Part III
Physical and Computational
Consequences

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- What is physical induction: a property P is satisfied in the first N experiments, then it is satisfied always.
- \bullet Comment: N should be sufficiently large.
- Theorem: $\forall \mathcal{T} \exists N \text{ s.t.}$ if for $o \in \mathcal{T}$, P(o) is satisfied in the first N experiments, then P(o) is satisfied always.
- Notation: $s \stackrel{\text{def}}{=} s_1 s_2 \dots$, where:
 - $s_i = T$ if P(o) holds in the *i*-th experiment, and
 - $s_i = F$ if $\neg P(o)$ holds in the *i*-th experiment.
- Proof: $A_n \stackrel{\text{def}}{=} \{ o : s_1 = \ldots = s_n = T \& \exists m (s_m = F) \};$ then $A_n \supseteq A_{n+1}$ and $\cup A_n = \emptyset$ so $\exists N (A_N \cap \mathcal{T} = \emptyset).$
- Meaning of $A_N \cap \mathcal{T} = \emptyset$: if $o \in \mathcal{T}$ and $s_1 = \ldots = s_N = T$, then $\neg \exists m (s_m = F)$, i.e., $\forall m (s_m = T)$.

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- - Main *objectives* of science:
 - quaranteed estimates for physical quantities;
 - quaranteed predictions for these quantities.
 - *Problem:* estimation and prediction are ill-posed.
 - Example:
 - measurement devices are inertial;
 - hence suppress high frequencies ω ;
 - so $\varphi(x)$ and $\varphi(x) + \sin(\omega \cdot t)$ are indistinguishable.
 - Existing approaches:
 - statistical regularization (filtering);
 - Tikhonov regularization (e.g., $|\dot{x}| \leq \Delta$);
 - expert-based regularization.
 - Main problem: no guarantee.

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- State estimation an ill-posed problem:
 - Measurement f: state $s \in S \to \text{observation } r = f(s) \in R$.
 - In principle, we can reconstruct $r \to s$: as $s = f^{-1}(r)$.
 - Problem: small changes in r can lead to huge changes in s (f^{-1} not continuous).
- Theorem:
 - Let S be a definably separable metric space.
 - Let \mathcal{T} be a set of physically meaningful elements of S.
 - Let $f: S \to R$ be a continuous 1-1 function.
 - Then, the inverse mapping $f^{-1}: R \to S$ is *continuous* for every $r \in f(\mathcal{T})$.

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26. Everything Is Related: Einstein-Podolsky-Rosen (EPR) Paradox

- Due to *Relativity Theory*, two spatially separated simultaneous events cannot influence each other.
- Einstein, Podolsky, and Rosen intended to show that in quantum physics, such influence is possible.
- In formal terms, let x and x' be measured values at these two events.
- Independence means that possible values of x do not depend on x', i.e., $\mathcal{T} = X \times X'$ for some X and X'.
- Physical induction implies that the pair (x, x') belongs to a set S of physically meaningful pairs.
- Theorem. A set \mathcal{T} os physically meaningful pairs cannot be represented as $X \times X'$.



• Thus, everything is related – but we probably can't use this relation to pass information (\mathcal{T} isn't computable).

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27. When to Stop an Iterative Algorithm?

- Situation in numerical mathematics:
 - we often know an iterative process whose results x_k are known to converge to the desired solution x,
 - but we do not know when to stop to guarantee that

$$d_X(x_k, x) \le \varepsilon.$$

- Heuristic approach: stop when $d_X(x_k, x_{k+1}) \leq \delta$ for some $\delta > 0$.
- Example: in physics, if 2nd order terms are small, we use the linear expression as an approximation.



- Let $\{x_k\} \in \mathcal{T}$, k be an integer, and $\varepsilon > 0$ a real number.
- We say that x_k is ε -accurate if $d_X(x_k, \lim x_p) \leq \varepsilon$.
- Let $d \ge 1$ be an integer.
- By a stopping criterion, we mean a function $c: X^d \to R_0^+$ that satisfies the following two properties:
 - If $\{x_k\} \in \mathcal{T}$, then $c(x_k, \ldots, x_{k+d-1}) \to 0$.
 - If for some $\{x_n\} \in \mathcal{T}$ and $k, c(x_k, \dots, x_{k+d-1}) = 0$, then $x_k = \dots = x_{k+d-1} = \lim x_p$.
- Result: Let c be a stopping criterion. Then, for every $\varepsilon > 0$, there exists a $\delta > 0$ such that
 - if $c(x_k, \ldots, x_{k+d-1}) \leq \delta$, and the sequence $\{x_n\}$ is physically meaningful,
 - then x_k is ε -accurate.

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Relation with Randomness

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29. Towards Relation with Randomness

- If a sequence s is random, it satisfies all the probability laws such as the law of large numbers.
- If a sequence satisfies all probability laws, then for all practical purposes we can consider it random.
- Thus, we can define a sequence to be random if it satisfies all probability laws.
- A probability law is a statement S which is true with probability 1: P(S) = 1.
- So, a sequence is random if it belongs to all definable sets of measure 1.
- A sequence belongs to a set of measure 1 iff it does not belong to its complement C = -S with P(C) = 0.
- So, a sequence is random if it does not belong to any definable set of measure 0.



30. Randomness and Kolmogorov Complexity

- Different definabilities lead to different randomness.
- When definable means computable, randomness can be described in terms of Kolmogorov complexity

$$K(x) \stackrel{\text{def}}{=} \min\{\text{len}(p) : p \text{ generates } x\}.$$

• Crudely speaking, an infinite string $s = s_1 s_2 \dots$ is random if, for some constant C > 0, we have

$$\forall n (K(s_1 \dots s_n) \geq n - C).$$

• Indeed, if a sequence $s_1 ldots s_n$ is truly random, then the only way to generate it is to explicitly print it:

$$print(s_1 \dots s_n).$$

• In contrast, a sequence like 0101...01 generated by a short program is clearly not random.

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31. From Kolmogorov-Martin-Löf Theoretical Randomness to a More Physical One

- The above definition means that (definable) events with probability 0 cannot happen.
- In practice, physicists also assume that events with a *very small* probability cannot happen.
- For example, a kettle on a cold stove will not boil by itself but the probability is non-zero.
- If a coin falls head 100 times in a row, any reasonable person will conclude that this coin is not fair.
- It is not possible to formalize this idea by simply setting a threshold $p_0 > 0$ below which events are not possible.
- Indeed, then, for N for which $2^{-N} < p_0$, no sequence of N heads or tails would be possible at all.



32. From Kolmogorov-Martin-Löf Theoretical Randomness to a More Physical One (cont-d)

- We cannot have a universal threshold p_0 such that events with probability $\leq p_0$ cannot happen.
- However, we know that:
 - for each decreasing $(A_n \supseteq A_{n+1})$ sequence of properties A_n with $\lim p(A_n) = 0$,
 - there exists an N above which a truly random sequence cannot belong to A_N .
- Resulting definition: we say that \mathcal{R} is a set of random elements if
 - for every definable decreasing sequence $\{A_n\}$ for which $\lim P(A_n) = 0$,
 - there exists an N for which $\mathcal{R} \cap A_N = \emptyset$.

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- Let \mathcal{R}_K denote the set of all elements which are random in Kolmorogov-Martin-Löf sense. Then:
- Every set of random elements consists of physically meaningful elements.
- For every set \mathcal{T} of physically meaningful elements, the intersection $\mathcal{T} \cap \mathcal{R}_K$ is a set of random elements.
- Proof: When A_n is definable, for $D_n \stackrel{\text{def}}{=} \bigcap_{i=1}^n A_i \bigcap_{i=1}^\infty A_i$, we have $D_n \supseteq D_{n+1}$ and $\bigcap_{i=1}^\infty D_n = \emptyset$, so $P(D_n) \to 0$.
- Therefore, there exists an N for which the set of random elements does not contain any elements from D_N .
- Thus, every set of random elements indeed consists of physically meaningful elements.

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35. A Formal Definition of Definable Sets

- Let \mathcal{L} be a theory.
- Let P(x) be a formula from \mathcal{L} for which the set $\{x \mid P(x)\}$ exists.
- We will then call the set $\{x \mid P(x)\}\ \mathcal{L}$ -definable.
- Crudely speaking, a set is \mathcal{L} -definable if we can explicitly define it in \mathcal{L} .
- All usual sets are definable: \mathbb{N} , \mathbb{R} , etc.
- Not every set is \mathcal{L} -definable:
 - every \mathcal{L} -definable set is uniquely determined by a text P(x) in the language of set theory;
 - there are only countably many texts and therefore, there are only countably many \mathcal{L} -definable sets;
 - so, some sets of natural numbers are not definable.

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36. How to Prove Results About Definable Sets

- Our objective is to be able to make mathematical statements about \mathcal{L} -definable sets. Therefore:
 - in addition to the theory \mathcal{L} ,
 - we must have a stronger theory \mathcal{M} in which the class of all \mathcal{L} -definable sets is a countable set.
- For every formula F from the theory \mathcal{L} , we denote its Gödel number by $\lfloor F \rfloor$.
- We say that a theory \mathcal{M} is stronger than \mathcal{L} if:
 - $-\mathcal{M}$ contains all formulas, all axioms, and all deduction rules from \mathcal{L} , and
 - \mathcal{M} contains a predicate def(n, x) such that for every formula P(x) from \mathcal{L} with one free variable,

$$\mathcal{M} \vdash \forall y (\operatorname{def}(\lfloor P(x) \rfloor, y) \leftrightarrow P(y)).$$



- As \mathcal{M} , we take \mathcal{L} plus all above equivalence formulas.
- Is \mathcal{M} consistent?
- Due to compactness, we prove that for any $P_1(x), \ldots, P_m(x), \mathcal{L}$ is consistent with the equivalences corr. to $P_i(x)$.
- Indeed, we can take

 $def(n, y) \leftrightarrow (n = |P_1(x)| \& P_1(y)) \lor ... \lor (n = |P_m(x)| \& P_m(y)).$

- This formula is definable in \mathcal{L} and satisfies all m equivalence properties.
- Thus, the existence of a stronger theory is proven.
- The notion of an \mathcal{L} -definable set can be expressed in \mathcal{M} : S is \mathcal{L} -definable iff $\exists n \in \mathbb{N} \, \forall y \, (\text{def}(n, y) \leftrightarrow y \in S)$.
- So, all statements involving definability become statements from the \mathcal{M} itself, not from metalanguage.

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- Statement: $\forall \varepsilon > 0$, there exists a set \mathcal{T} for which $\underline{P}(\mathcal{T}) \geq 1 \varepsilon$.
- There are countably many definable sequences $\{A_n\}$: $\{A_n^{(1)}\}, \{A_n^{(2)}\}, \ldots$
- For each k, $P\left(A_n^{(k)}\right) \to 0$ as $n \to \infty$.
- Hence, there exists N_k for which $P\left(A_{N_k}^{(k)}\right) \leq \varepsilon \cdot 2^{-k}$.
- We take $\mathcal{T} \stackrel{\text{def}}{=} \bigcup_{k=1}^{\infty} A_{N_k}^{(k)}$. Since $P\left(A_{N_k}^{(k)}\right) \leq \varepsilon \cdot 2^{-k}$, we have

$$\overline{P}\left(\bigcup_{k=1}^{\infty} A_{N_k}^{(k)}\right) \le \sum_{k=1}^{\infty} P\left(A_{N_k}^{(k)}\right) \le \sum_{k=1}^{\infty} \varepsilon \cdot 2^{-k} = \varepsilon.$$

• Hence, $\underline{P}(\mathcal{T}) = 1 - \overline{P}\left(\bigcup_{k=1}^{\infty} A_{N_k}^{(k)}\right) \ge 1 - \varepsilon$.

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• For each i, we can compute $\varepsilon' \in (\varepsilon/2, \varepsilon)$ for which $B_i \stackrel{\text{def}}{=} \{x : d(x, x_i) \leq \varepsilon'\}$ is a computable compact set.

- It is possible to algorithmically compute the minimum of a function on a computable compact set.
- Thus, we can compute $m_i \stackrel{\text{def}}{=} \min\{|f(x)| : x \in B_i\}.$
- Since $f \in T$, similarly to the previous proof, we can prove that $\exists N \, \forall f \in T \, \forall i \, (m_i = 0 \, \lor \, m_i \geq 2^{-N})$.
- Comp. m_i w/acc. $2^{-(N+2)}$, we check $m_i = 0$ or $m_i > 0$.
- Let's prove that $d_H(R, \{x_i : m_i = 0\}) \leq \varepsilon$, i.e., that $\forall i \ (m_i = 0 \Rightarrow \exists x \ (f(x) = 0 \& d(x, x_i) \leq \varepsilon))$ and $\forall x \ (f(x) = 0 \Rightarrow \exists i \ (m_i = 0 \& d(x, x_i) \leq \varepsilon))$.

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Finding Roots: Proof (cont-d)

- $m_i = 0$ means $\min\{|f(x)| : x \in B_i \stackrel{\text{def}}{=} B_{\varepsilon'}(x_i)\} = 0.$
- Since the set K is compact, this value 0 is attained, i.e., there exists a value $x \in B_i$ for which f(x) = 0.
- From $x \in B_i$, we conclude that $d(x, x_i) \leq \varepsilon'$ and, since $\varepsilon' < \varepsilon$, that $d(x, x_i) < \varepsilon$.
- Thus, x_i is ε -close to the root x.
- Vice versa, let x be a root, i.e., let f(x) = 0.
- Since the points x_i form an $(\varepsilon/2)$ -net, there exists an index i for which $d(x, x_i) \leq \varepsilon/2$.
- Since $\varepsilon/2 < \varepsilon'$, this means that $d(x, x_i) \leq \varepsilon'$ and thus, $x \in B_i$.
- Therefore, $m_i = \min\{|f(x)| : x \in B_i\} = 0$. So, the root x is ε -close to a point x_i for which $m_i = 0$.

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- *Known*: if a f is continuous and 1-1 on a compact, then f^{-1} is also continuous.
- Reminder: S is compact if and only if it is closed and for every ε , it has a finite ε -net.
- \bullet Given: the set X is definably separable.
- Means: \exists def. s_1, \ldots, s_n, \ldots everywhere dense in X.
- Solution: take $A_n \stackrel{\text{def}}{=} \bigcup_{i=1}^n B_{\varepsilon}(s_i)$.
- Since s_i are everywhere dense, we have $\cap A_n = \emptyset$.
- Hence, there exists N for which $A_N \cap \mathcal{T} = \emptyset$.
- Since $A_N = -\bigcup_{i=1}^N B_{\varepsilon}(s_i)$, this means $\mathcal{T} \subseteq \bigcup_{i=1}^N B_{\varepsilon}(s_i)$.
- Hence $\{s_1, \ldots, s_N\}$ is an ε -net for \mathcal{T} . Q.E.D.

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- Let T consist of physically meaningful elements. Let us prove that $T \cap \mathcal{R}_K$ is a set of random elements.
- If $A_n \supseteq A_{n+1}$ and $P\left(\bigcap_{n=1}^{\infty} A_n\right) = 0$, then for $B_m \stackrel{\text{def}}{=} A_m \bigcap_{n=1}^{\infty} A_n$, we have $B_m \supseteq B_{m+1}$ and $\bigcap_{n=1}^{\infty} B_n = \emptyset$.
- Thus, by definition of a set consisting of physically meaningful elements, we conclude that $B_N \cap T = \emptyset$.
- Since $P\left(\bigcap_{n=1}^{\infty} A_n\right) = 0$, we also know that $\left(\bigcap_{n=1}^{\infty} A_n\right) \cap \mathcal{R}_K = \emptyset$.
- Thus, $A_N = B_N \cup \left(\bigcap_{n=1}^{\infty} A_n\right)$ has no common elements with the intersection $T \cap \mathcal{R}_K$. Q.E.D.

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43.

we have

- As \mathcal{A} , given an instance i, we simply produce the result ω_i of the i-th experiment.
- Let us prove, by contradiction, that for every $\varepsilon > 0$ and for every n, there exists an integer N > n for which

$$\#\{i \leq N : i \in S_{\mathcal{P}} \& \omega_i = s_{\mathcal{P},i}\} > (1-\varepsilon) \cdot \#\{i \leq N : i \in S_{\mathcal{P}}\}.$$
• The assumption that this property is not satisfied means that for some $\varepsilon > 0$ and for some integer n ,

$$\forall N_{\geq n} \# \{ i \leq N : i \in S_{\mathcal{P}} \& \omega_i = s_{\mathcal{P},i} \} \leq (1 - \varepsilon) \cdot \# \{ i \leq N : i \in S_{\mathcal{P}} \}.$$
• Let $T \stackrel{\text{def}}{=} \{ x : \# \{ i \leq N : i \in S_{\mathcal{P}} \& x_i = s_{\mathcal{P},i} \} \leq$

- $(1 \varepsilon) \cdot \#\{i \le N : i \in S_{\mathcal{P}}\} \text{ for all } N \ge n\}.$
- We will prove that this set T is a physical theory (in the sense of the above definition); then $\omega \notin T$.

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- Reminder: $T = \{x : \#\{i \le N : i \in S_{\mathcal{P}} \& x_i = s_{\mathcal{P},i}\} \le (1 \varepsilon) \cdot \#\{i \le N : i \in S_{\mathcal{P}}\} \text{ for all } N \ge n\}.$
- By definition, a physical theory is a set which is nonempty, closed, nowhere dense, and definable.
- Non-emptiness is easy: the sequence $x_i = \neg s_{\mathcal{P},i}$ for $i \in S_{\mathcal{P}}$ belongs to T.
- One can prove that T is closed, i.e., if $x^{(m)} \in T$ for which $x^{(m)} \to \omega$, then $x \in T$.
- Nowhere dense means that for every finite sequence $x_1 \dots x_m$, there exists a continuation $x \notin T$.
- Indeed, for extension, we can take $x_i = s_{\mathcal{P},i}$ if $i \in S_{\mathcal{P}}$.
- ullet Finally, we have an explicit definition of T, so T is definable.

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• Let us assume that $P \neq NP$; we want to prove that for every feasible ph-algorithm \mathcal{A} , it is not possible to have

 $\forall N \, (\#\{i \leq N : i \in S_{\mathcal{P}} \& \mathcal{A}(\omega, i) = s_{\mathcal{P},i}\} = \#\{i \leq N : i \in S_{\mathcal{P}}\}).$

• Let us consider, for each feasible ph-algorithm \mathcal{A} ,

 $T(\mathcal{A}) \stackrel{\text{def}}{=} \{x : \#\{i \leq N : i \in S_{\mathcal{P}} \& \mathcal{A}(x,i) = s_{\mathcal{P},i}\} = 1\}$ $\#\{i \leq N : i \in S_{\mathcal{P}}\}$ for all $N\}$.

- Similarly to the proof of the main result, we can show that this set T(A) is closed and definable.
- To prove that T(A) is nowhere dense, we extend $x_1 \dots x_m$ by 0s; then $x \in T$ would mean P=NP.
- If $T(\mathcal{A}) \neq \emptyset$, then $T(\mathcal{A})$ is a theory, so $\omega \notin T(\mathcal{A})$.
- If $T(A) = \emptyset$, this also means that A does not solve all instances of the problem \mathcal{P} – no matter what ω we use.

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- Let us assume that no non-oracle feasible algorithm δ -solves the problem \mathcal{P} .
- Let's consider, for each N_0 and feasible ph-alg. \mathcal{A} ,

$$T(\mathcal{A}, N_0) \stackrel{\text{def}}{=} \{x : \#\{i \le N : i \in S_{\mathcal{P}} \& \mathcal{A}(x, i) = s_{\mathcal{P}, i}\} > \delta \cdot \#\{i \le N : i \in S_{\mathcal{P}}\} \text{ for all } N \ge N_0\}.$$

- We want to prove that $\forall N_0 (\omega \notin T(\mathcal{A}, N_0))$.
- Similarly to the proof of the Main Result, we can show that $T(A, N_0)$ is closed and definable.
- To prove that $T(A, N_0)$ is nowhere dense, we extend $x_1 \dots x_m$ by 0s.
- If $T(\mathcal{A}, N_0) \neq \emptyset$, then $T(\mathcal{A}, N_0)$ is a theory hence $\omega \notin T(\mathcal{A}, N_0)$.
- If $T(A, N_0) = \emptyset$, then also $\omega \notin T(A, N_0)$.

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