

Towards Optimal Representation and Processing of Uncertainty for Decision Making, on the Example of Economics-Related Heavy-Tailed Distributions

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Formulation of the ...

Normal distributions ...

In Many Practical ...

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1. Formulation of the Problem

- Traditionally, most statistical techniques assume that the random variables are normally distributed.
- For such distributions:
 - a natural characteristic of the “average” value is the mean, and
 - a natural characteristic of the deviation from the average is the variance.
- In practice, we encounter *heavy-tailed* distributions, with infinite variance; what are analogs of:
 - “average” and deviation from average?
 - correlation?
 - how to take into account interval and fuzzy uncertainty?

2. Normal Distributions Are Most Widely Used

- Most statistical techniques assume that the random variables are normally distributed:

$$\rho(x) = \frac{1}{\sqrt{2\pi \cdot V}} \cdot \exp\left(-\frac{(x - m)^2}{2V}\right).$$

- For such distributions:
 - a natural characteristic of the “average” value is the mean $m \stackrel{\text{def}}{=} E[x]$, and
 - a natural characteristic of the deviation from the average is the variance $V \stackrel{\text{def}}{=} E[(x - m)^2]$.
- It is known that a normal distribution is uniquely determined by m and V .
- Thus, each characteristic (mode, median, etc.) is uniquely determined by m and V .

3. Estimating the Values of the Characteristics: Case of Normal Distributions

- We have a sample consisting of the values x_1, \dots, x_n .
- We can use the Maximum Likelihood Method: m and V maximizing

$$L = \rho(x_1) \cdot \dots \cdot \rho(x_n) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi \cdot V}} \cdot \exp\left(-\frac{(x_i - m)^2}{2V}\right).$$

- Maximizing L is equivalent to minimizing

$$\psi \stackrel{\text{def}}{=} -\ln(L) = \sum_{i=1}^n \left[\frac{1}{2} \cdot \ln(2\pi \cdot V) + \frac{(x_i - m)^2}{2V} \right].$$

- Equating derivatives to 0, we get:

$$m = \frac{1}{n} \cdot \sum_{i=1}^n x_i; \quad V = \frac{1}{n} \cdot \sum_{i=1}^n (x_i - m)^2.$$

4. In Many Practical Situations, We Encounter Heavy-Tailed Distributions

- In the 1960s, Benoit Mandelbrot empirically studied fluctuations.
- He showed that larger-scale fluctuations follow the power-law distribution $\rho(x) = A \cdot x^{-\alpha}$, with $\alpha \approx 2.7$.
- For this distribution, variance is infinite.
- Such distributions are called *heavy-tailed*.
- Similar heavy-tailed laws were empirically discovered in other application areas.
- These result led to the formulation of *fractal theory*.
- Since then, similar heavy-tailed distributions have been empirically found:
 - in other financial situations and
 - in many other application areas.

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5. First Problem: How to Characterize Such Distributions?

- Usually, *variance* is used to describe deviation from the average.
- For heavy-tailed distributions, variance is *infinite*.
- So, we *cannot* use variance to describe the deviation from the “average”.
- Thus, we need to come up with *other* characteristics for describing this deviation.
- We will *describe* such characteristics in the first part of this talk.
- We will also describe *how we can estimate* these characteristics.

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6. Need to Take into Account Interval Uncertainty

- *Reminder:* $m = \frac{1}{n} \cdot \sum_{i=1}^n x_i$, $V = \frac{1}{n} \cdot \sum_{i=1}^n (x_i - m)^2$.
- In practice, we often know approximate values $\tilde{x}_i \approx x_i$.
- Sometimes, we know the probabilities of different values of the approximation error $\Delta x_i \stackrel{\text{def}}{=} \tilde{x}_i - x_i$.
- Often, we only know the upper bound Δ_i : $|\Delta x_i| \leq \Delta_i$.
- So, we only know that $x_i \in \mathbf{x}_i = [\tilde{x}_i - \Delta_i, \tilde{x}_i + \Delta_i]$.
- For each estimator $C(x_1, \dots, x_n)$, different $x_i \in \mathbf{x}_i$ lead, in general, to different values $C(x_1, \dots, x_n)$.
- Thus, we must find the range:
$$\mathbf{C} = [\underline{C}, \overline{C}] = \{C(x_1, \dots, x_n) : x_1 \in \mathbf{x}_1, \dots, x_n \in \mathbf{x}_n\}.$$
- This *interval computations* problem is, in general, NP-hard.

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7. How to Describe Deviation from the “Average” for Heavy-Tailed Distributions: Analysis

- A standard way to describe preferences of a decision maker is to use the notion of *utility* u .
- According to decision theory, a user prefers an alternative for which the expected value $\sum_{i=1}^n p_i \cdot u_i \rightarrow \max$.
- Alternative, the expected value $\sum_{i=1}^n p_i \cdot U_i$ of the *disutility* $U \stackrel{\text{def}}{=} -u$ is the smallest possible.
- If we replace $x_i \rightarrow m \approx x_i$, there is disutility $U(x_i - m)$.
- So, we choose m s.t. $\frac{1}{n} \cdot \sum_{i=1}^n U(x_i - m) \rightarrow \min$.
- The resulting minimum describes the deviation of the values from this “average”.

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8. Resulting Definitions

- Let $U : \mathbb{R} \rightarrow \mathbb{R}_0$ be a function for which:
 - $U(0) = 0$,
 - $U(d)$ is (non-strictly) increasing for $d \geq 0$, and
 - $U(d)$ is (non-strictly) decreasing for $d \leq 0$.
- For each sample x_1, \dots, x_n , by a U -estimate, we mean the value m_U that minimizes $\frac{1}{n} \cdot \sum_{i=1}^n U(x_i - m)$.
- By a U -deviation, we mean $V_U \stackrel{\text{def}}{=} \frac{1}{n} \cdot \sum_{i=1}^n U(x_i - m_U)$.
- When $U(x) = x^2$, m_U is mean, and V_U is variance.
- When $U(x) = |x|$, m_U is median, and V_U is average absolute deviation (AAD) $V_U = \frac{1}{n} \cdot \sum_{i=1}^n |x_i - m_U|$.

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9. These Are Estimates: What Statistical Characteristics Are They Estimating?

- Let $U : \mathbb{R} \rightarrow \mathbb{R}_0$ be a f-n for which $U(0) = 0$, and:
 - $U(d)$ is (non-strictly) increasing for $d \geq 0$, and
 - $U(d)$ is (non-strictly) decreasing for $d \leq 0$.
- For each distribution $\rho(x)$, by a U -mean, we mean the value m_U that minimizes the expected disutility

$$E[U(x - m)] = \int U(x - m) \cdot \rho(x) dx.$$

- By a U -deviation, we mean this expected disutility value value $E[U(x - m_U)]$.
- When $U(x) = x^2$, m_U is the expected value mean, and V_U is variance.
- When $U(x) = |x|$, m_U is the median, and V_U is MAD:

$$V_U = E[|x - m_U|] = \int |x - m_U| \cdot \rho(x) dx.$$

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10. How to Estimate m_U and V_U

- Once we compute m_U , the computation of $V_U = \frac{1}{n} \cdot \sum_{i=1}^n U(x_i - m_U)$ is straightforward.

- Estimating m_U means optimizing a function of a single variable $\frac{1}{n} \cdot \sum_{i=1}^n U(x_i - m) \rightarrow \min$.

- This optimization problem is equivalent to the Maximum Likelihood (ML): for $U(x) = -\ln(\rho_0(x))$,

$$L = \rho_0(x_1 - m) \cdot \dots \cdot \rho_0(x_n - m) \rightarrow \max \Leftrightarrow$$

$$\psi \stackrel{\text{def}}{=} -\ln(L) = \sum_{i=1}^n U(x_i - m) \rightarrow \min.$$

- Similar algorithms are used in *robust statistics*, as *M-methods*, which are mathematically equivalent to ML.

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11. Estimating the Heavy-Tailed-Related Deviation Characteristics under Interval Uncertainty: Analysis of the Problem

- When we know the exact values of x_i , we know how to compute $V_U = \min_m \frac{1}{n} \cdot \sum_{i=1}^n U(x_i - m)$.
- In practice, the values x_i are often only known with interval uncertainty.
- We only know the intervals $\mathbf{x}_i = [\underline{x}_i, \bar{x}_i]$ that contain the unknown values x_i .
- In this case, it is desirable to compute the range $\mathbf{V}_U = [\underline{V}_U, \bar{V}_U]$ of possible values of V_U when $x_i \in \mathbf{x}_i$. Here:
 - The value \underline{V}_U is the minimum of the function $V_U(x_1, \dots, x_n)$ when $x_i \in \mathbf{x}_i$.
 - The value \bar{V}_U is the maximum of the function $V_U(x_1, \dots, x_n)$ when $x_i \in \mathbf{x}_i$.

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12. Algorithm for Computing \underline{V}_U

- First, sort all $2n$ endpoints \underline{x}_i and \bar{x}_i into an increasing sequence $x_{(1)} \leq x_{(2)} \leq \dots \leq x_{(2n)}$.
- These values, with $x_{(0)} \stackrel{\text{def}}{=} -\infty$ and $x_{(2n+1)} \stackrel{\text{def}}{=} +\infty$, divide the real line into zones $[x_{(k)}, x_{(k+1)}]$, $k = 0, 1, \dots, 2n$.
- For each zone z , we select the values x_1, \dots, x_n as follows: for some value m (to be determined),
 - if $\bar{x}_i \leq r_{(k)}$, then we select $x_i = \bar{x}_i$;
 - if $r_{(k+1)} \leq \underline{x}_i$, then we select $x_i = \underline{x}_i$;
 - for all other i , we select $x_i = m$.
- Then, we take only the values for which $x_i \neq m$, and find their U -estimate m_U ; if $m_U \in z$, we compute V_U .
- The smallest of thus computed U -deviations is the desired value \underline{V}_U .

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13. Computation Time for This Algorithm

- Sorting takes $O(n \cdot \log(n))$ steps.
- After that, for each of $2n = O(n)$ zones, we need:
 - $O(n)$ steps to perform the computations and
 - the time – that we will denote by T_{exact} – to compute the U -estimate and U -deviation.
- Thus, the total computation time is equal to
$$O(n \cdot \log(n)) + O(n^2) + O(n) \cdot T_{\text{exact}} = O(n^2) + O(n) \cdot T_{\text{exact}}.$$
- Conclusion:
 - if we can compute V_U for exactly known x_i in polynomial time (e.g., linear), then
 - we can compute \underline{V}_U under interval (hence fuzzy) uncertainty also in polynomial time (e.g., quadratic).

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14. Computing \bar{V}_U : Analysis of the Problem

- *Fact:* the maximum \bar{V}_U is attained:
 - if $\bar{x}_i \leq m$, for $x_i = \underline{x}_i$;
 - if $m \leq \underline{x}_i$, for $x_i = \bar{x}_i$;
 - if $\underline{x}_i \leq m \leq \bar{x}_i$, for $x_i = \underline{x}_i$ or $x_i = \bar{x}_i$.
- *Resulting algorithm:*
 - try all possible combinations of endpoints that satisfy the above conditions, and
 - select the largest of the resulting values V_U .
- *Problem:* we may need 2^n combinations, too long already for $n \approx 300$.
- *Explanation:* even for $U(d) = d^2$, the problem of computing \bar{V}_U is NP-hard.

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15. Case when a Feasible Algorithm Is Possible

- *Reminder:* we consider cases where:
 - if $\bar{x}_i \leq m$, for $x_i = \underline{x}_i$;
 - if $m \leq \underline{x}_i$, for $x_i = \bar{x}_i$;
 - if $\underline{x}_i \leq m \leq \bar{x}_i$, for $x_i = \underline{x}_i$ or $x_i = \bar{x}_i$.
- *Situation.* For some C , every group of $> C$ intervals has an empty intersection.
- *Algorithm:* for each zone z , we consider case $m \in z$.
- For each zone, there are $\leq C$ intervals for which
$$\underline{x}_i \leq m \leq \bar{x}_i.$$
- So we need to check $\leq 2^C$ combinations for each zone.
- Since C is a constant, $2^C = O(1)$.

16. Resulting Algorithm for Computing \bar{V}_U

- First, we sort all endpoints \underline{x}_i and \bar{x}_i into an increasing sequence, and add $x_{(0)} = -\infty$ and $x_{(2n+1)} = +\infty$:
$$-\infty = x_{(0)} \leq x_{(1)} \leq x_{(2)} \leq \dots \leq x_{(2n)} \leq x_{(2n+1)} = +\infty.$$
- For each zone $[x_{(k)}, x_{(k+1)}]$, we do the following:
 - if $\bar{x}_i \leq r_{(k)}$, then we select $x_i = \underline{x}_i$;
 - if $r_{(k+1)} \leq \underline{x}_i$, then we select $x_i = \bar{x}_i$;
 - for all other i , we select either $x_i = \underline{x}_i$ or $x_i = \bar{x}_i$.
- For each zone, we have $\leq C$ indices i that allow two selections, so we thus get $\leq 2^C$ selections.
- For each of these selections, we compute the U -deviation.
- The largest of these V_U is the desired value \bar{V}_U .
- This algorithm requires time $O(n^2) + O(n) \cdot T_{\text{exact}}$.

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17. When a Feasible Algorithm Is Possible

- *2nd case:* no interval is a proper subinterval of another:
 $[\underline{x}_i, \bar{x}_i] \not\subseteq (\underline{x}_j, \bar{x}_j)$ for all i and j .

- *Example:* measurements made by the same instrument.

- Under this property, lexicographic order

$$[\underline{x}_i, \bar{x}_i] \leq [\underline{x}_j, \bar{x}_j] \Leftrightarrow ((\underline{x}_i < \underline{x}_j) \vee (\underline{x}_i = \underline{x}_j \ \& \ \bar{x}_i < \bar{x}_j))$$

sorts the intervals by both endpoints:

$$\underline{x}_1 \leq \underline{x}_2 \leq \dots \leq \underline{x}_n; \quad \bar{x}_1 \leq \bar{x}_2 \leq \dots \leq \bar{x}_n.$$

- One can prove that, for some k , the maximum is attained at a tuple $(\underline{x}_1, \dots, \underline{x}_k, \bar{x}_{k+1}, \dots, \bar{x}_n)$.
- There are $n + 1$ such tuples, so we have a polynomial-time algorithm.
- Similar arguments can be made when the intervals can be divided into m groups with this property.

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18. Resulting Algorithms for Computing \bar{V}_U

- *Applicable*: when $[\underline{x}_i, \bar{x}_i] \not\subseteq (\underline{x}_j, \bar{x}_j)$ for all i and j .
- First, we sort all the intervals in lexicographic order

$$[\underline{x}_i, \bar{x}_i] \leq [\underline{x}_j, \bar{x}_j] \Leftrightarrow ((\underline{x}_i < \underline{x}_j) \vee (\underline{x}_i = \underline{x}_j \ \& \ \bar{x}_i < \bar{x}_j)).$$

- Then, we compute V_U for all $n + 1$ tuples of the form $(\underline{x}_1, \dots, \underline{x}_k, \bar{x}_{k+1}, \dots, \bar{x}_n)$, with $k = 0, 1, \dots, n$.
- The largest of thus computed U -deviations is the desired value \bar{V}_U .
- This algorithm requires time

$$O(n \cdot \log(n)) + O(n) \cdot T_{\text{exact}}.$$

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19. Algorithms for Computing \bar{V}_U (cont-d)

- *Applicable*: all intervals can be divided into m groups each of which satisfies the no-subinterval property.
- We sort all intervals within each group in lexicographic order.
- For each group $j = 1, \dots, m$, with $n_j \leq n$ elements, we consider $n_j + 1 \leq n + 1$ tuples of the form

$$(\underline{x}_1, \dots, \underline{x}_{k_j}, \bar{x}_{k_j+1}, \dots, \bar{x}_n).$$

- We consider all possible combinations of such tuples corresponding to all possible vectors (k_1, \dots, k_m) .
- For each of these $\leq n^m$ vectors, we compute V_U .
- The largest of these V_U is the desired value \bar{V}_U .
- This algorithm requires time

$$O(n \cdot \log(n)) + O(n^m) \cdot T_{\text{exact}}.$$

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20. What Are the Reasonable Measures of Dependence for Heavy-Tailed Distributions?

- In the traditional statistics, a reasonable measure of dependence is the correlation

$$\rho_{xy} = \frac{\frac{1}{n} \cdot \sum_{i=1}^n (x_i - m_x) \cdot (y_i - m_y)}{\sqrt{V_x \cdot V_y}}.$$

- For heavy-tailed distributions, variances are infinite, so this formula cannot be applied.
- *Possibility:* use Kendall's tau, the proportion of pairs (i, j) for which x and y change in the same direction:
either $(x_i \leq x_j \ \& \ y_i \leq y_j)$ or $(x_j \leq x_i \ \& \ y_j \leq y_i)$.
- *Remaining problem:* what if we are interested only in linear dependencies?

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21. Proposed Definition

- *Idea:* c describes how much disutility decreases when we use x_i to help predict y_i :

$$c \stackrel{\text{def}}{=} \frac{V_U(y) - V_{U,\mathcal{F}}(y|x)}{V_U(y)},$$

where

$$V_U(y) \stackrel{\text{def}}{=} \min_m \frac{1}{n} \cdot \sum_{i=1}^n U(y_i - m)$$

and

$$V_{U,\mathcal{F}}(y|x) \stackrel{\text{def}}{=} \min_{f \in \mathcal{F}} \frac{1}{n} \cdot \sum_{i=1}^n U(y_i - f(x_i)).$$

- The function f at which the minimum is attained is called \mathcal{F} -regression.
- When $U(d) = d^2$ and \mathcal{F} is the class of all linear functions, $c = \rho^2$.

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22. Discussion

- For normal distributions and linear functions, correlation is symmetric:
 - if we can reconstruct y_i from x_i ,
 - then we can reconstruct x_i from y_i .
- Our definition is, in general, not symmetric.
- This asymmetry make perfect sense.
- For example, suppose that $y_i = x_i^2$:
 - then, if we know x_i , then we can uniquely reconstruct y_i ;
 - however, if we know y_i , we can only reconstruct x_i modulo sign.
- *Remaining open problem*: estimate the above measures of dependence under interval uncertainty.

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