Exact Bounds for Interval and Fuzzy Functions Under Monotonicity Constraints, with Potential Applications to Biostratigraphy

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Main ideas behind The practical . . . Traditional approach . . Interval uncertainty Fuzzy uncertainty Towards the precise . . . Other practical . . . Additional complexity First Problem: . . . Second Problem: . . . Algorithms for . . . Possibility of . . . Algorithms for . . . From Monotonicity to ... Future Work Acknowledgments **>>** Page 1 of 19 Go Back Full Screen Close

The notion of a

1. Biostratigraphy is important

- Biostratigraphy is concerned with the stratigraphic analysis of rocks based on their paleontologic content.
- Generally speaking, stratigraphy analyses the rock strata and is concerned with their succession and age relationship.
- All aspects of rocks as strata are, however, of concern for stratigraphy.
- The analysis of fossil can also provide useful information regarding the environment in which rocks have accumulated.
- \bullet $\it Example:$ a coral is an unambiguous indication of a warm ocean.



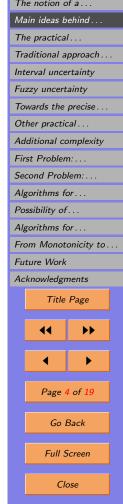
2. The notion of a stratigraphic map

- *Problem:* how to determine the age of the fossil?
- Fact: in a normal sequence, the age increases with the depth in the well that penetrates that sequence.
- Solution: if the rock accumulation rate is known, the depth x at which the fossil species was found can be used to determine its age y.
- Stratigraphic map: the dependence between the depth x and the age y.
- Once we know the depth x and the stratigraphic map y = f(x), we can determine the age y of the fossil.
- Complication: a stratigraphic map is different for different locations, because it depends on the geological history (of accumulation rates) at this location.



3. Main ideas behind constructing a stratigraphic map

- \bullet In every area, we have several fossils whose age y has been determined.
- For the selected fossil, we know the depth x_i at which it was found, and we know the estimated age y_i .
- Based on the points (x_i, y_i) , we must find the desired dependence y = f(x).
- Since deeper layers are older, we should have a monotonic (increasing) dependence y = f(x) for which $y_i = f(x_i)$.
- So, ideally, we should have a monotonic function that passes through all the points.



4. The practical construction of a stratigraphic map is not that easy

- The conclusion about monotonicity is based on the *idealized assumption*:
- y_i is the age of the oldest (for wells, youngest) of many fossils of this type.
- For some types, we do have many fossils, so the oldest of these fossils represents a reasonable size sample.
- Corresponing values x_i and y_i are highly reliable.
- For other types of fossils, however, we may have only a few sample fossils of this type in a given area.
- So, x_i and y_i are not very accurate.
- As a result of this inaccuracy, in practice, it is usually impossible to have a monotonic dependence that passes exactly through all the points (x_i, y_i) .

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5. Traditional approach and its drawbacks

- Problem: few-sample data points do not fit to a monotonic curve.
- *Idea*: we select a threshold n_0 and only consider points (x_i, y_i) which came from samples of size $\geq n_0$.
- Remaining problems: we
 - ignore all the points (x_i, y_i) with lower accuracy, and
 - consider all the points with higher accuracy as exact, ignoring the fact that these points are not absolutely accurate.
- Objective: it is desirable to use the ignored information, to get a more accurate stratigraphic map.



6. Interval uncertainty

- For few-sample fossil types, the actual oldest age y_i is different from the estimated oldest age \widetilde{y}_i .
- Due to chaotic rock movements, the ideal depth x_i differs from the depth \widetilde{x}_i at which the fossil was found.
- Problem: we have too few fossils to determine the probability of different values $\Delta x_i \stackrel{\text{def}}{=} \widetilde{x}_i x_i$ and $\Delta y_i \stackrel{\text{def}}{=} \widetilde{y}_i y_i$.
- What we do have: expert estimates for the upper bound Δ_i on Δx_i .
- Interval uncertainty: for each fossil type i, we know the intervals $\mathbf{x}_i = [\underline{x}_i, \overline{x}_i] = [\widetilde{x}_i \Delta_i, \widetilde{x}_i + \Delta_i]$ and, similarly, $\mathbf{y}_i = [\underline{y}_i, \overline{y}_i]$ that contain the actual (unknown) values of x_i and y_i .



7. Fuzzy uncertainty

- Interval information comes from the guaranteed bound on Δx_i and Δy_i .
- Additional information: often, an expert can also provide bounds that contain Δy_i with a certain degree of confidence.
- Usually, we know several such bounding intervals corresponding to different degrees of confidence.
- Such a *nested family* of intervals is also called a *fuzzy set*, because it turns out to be equivalent to a more traditional definition of fuzzy set:
- If a traditional fuzzy set is given, then:
 - different *intervals* from the nested family
 - can be viewed as α -cuts corresponding to different levels of uncertainty α .



8. Towards the precise formulation of the problem

- Interval uncertainty:
 - We know the *n* boxes $\mathbf{x}_i \times \mathbf{y}_i$ corresponding to different types of fossils.
 - We know that the monotonic dependence y = f(x) is such that $y_i = f(x_i)$ for some $(x_i, y_i) \in \mathbf{x}_i \times \mathbf{y}_i$.
 - Objective: to find, for every depth x, the bounds of the possible values of age y = f(x) for all the dependencies that are consistent with the given data.
- Fuzzy uncertainty:
 - For each degree of confidence α , we must solve the problem corresponding to the α -cut intervals.
 - Thus, for each x, we want to have a fuzzy set of possible values of f(x).



9. Other practical applications of the resulting mathematical problem

- \bullet $Spectral\ analysis:$ chemical species are identified by locating local maxima of the spectra.
- $\bullet \ \it Radioastronomy:$ sources of celestial radio emission and their subcomponents.
- Elementary particles are local maxima in the dependence of scattering intensity y on the energy x.
- Landscape analysis: mountain slopes.
- Financial analysis: growth or decline periods.
- Clustering: 1-D clusters are separated by local minima of the probability density.
- Comment: once we know how to check monotonicity, we can also find the local extrema as borders between monotonicity intervals.



10. Additional complexity

- Algorithms for solving the subproblem of checking motonoticity have been previously described.
- Additional complexity: it is possible to have several different ages $y_i < y_j$ for the same depth $x_i = x_j$.
- In mathematical terms: this means that the dependence y = f(x) is not necessarily a monotonic function.
- It may be a *limit* of the graphs of monotonic functions in the sense of Hausdorff metric.



11. First Problem: Checking Monotonicity

- By a monotonic dependence f, we mean the graph of a continuous mapping $m(s) = (m_1(s), m_2(s))$ from the real line \mathbb{R} to the plane \mathbb{R}^2 for which t < s implies that $m_1(t) \leq m_1(s)$ and $m_2(t) \leq m_2(s)$.
- We say that a monotonic dependence f is *consistent* with a box $\mathbf{x} \times \mathbf{y}$ if $f \cap (\mathbf{x} \times \mathbf{y}) \neq \emptyset$.
- By data d, we mean a finite collection of boxes.
- We say that the data is *consistent* if there exists a monotonic dependence that is consistent with all its boxes.
- Theorem. The data d is consistent \leftrightarrow for every i and j, $\overline{x}_i < \underline{x}_j$ implies $\underline{y}_i \leq \overline{y}_j$.

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12. Second Problem: Computing the Range of f(x) for Consistent Data

- Given:
 - the data $[\underline{x}_i,\overline{x}_i]\times [y_i,\overline{y}_i]\ (1\leq i\leq n)$ and
 - a real number x.
- Objective: to find the exact lower and upper bounds of the corresponding y over all the monotonic dependences that are consistent with this data:

$$\underline{f}(x) \stackrel{\text{def}}{=} \inf\{y : \exists f ((x,y) \in f \& Con(f,d))\}.$$

$$\overline{f}(x) \stackrel{\text{def}}{=} \sup\{y \,:\, \exists f\, ((x,y) \in f\,\&\, Con(f,d))\}.$$

• Solution:

$$\underline{f}(x) = \max_{i:\overline{x}_i < x} \underline{y}_i; \quad \overline{f}(x) = \min_{j:x < \underline{x}_j} \overline{y}_j.$$

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13. Algorithms for checking consistency

- Straightforward algorithm: checking, for every i and j, whether $\overline{x}_i < \underline{x}_j$ implies $y_i \leq \overline{y}_j$.
- Problem: we need $O(n^2)$ comparisons too long.
- Equivalent condition: $\forall i, \ \underline{y}_i \leq \min_{j:\underline{x}_i \geq \overline{x}_i} \overline{y}_j$.
- Resulting fast algorithm:
 - Sort the values \underline{x}_i ($O(n \cdot \log(n))$ steps).
 - For i = n, ..., 1, compute $M_i \stackrel{\text{def}}{=} \min(\overline{y}_n, \overline{y}_{n-1}, ..., \overline{y}_i)$:

$$M_n = \overline{y}_n; \quad M_{i-1} = \min(M_i, \overline{y}_{i-1}).$$

- For each i from 1 to n, use binary search to find m(i) s.t. $\underline{x}_{m(i)-1} < \overline{x}_i \leq \underline{x}_{m(i)}$.
- For every i from 1 to n, check $y_i \leq M_{m(i)}$.
- \bullet The data is consistent \leftrightarrow all these inequalities hold.
- This algorithm requires $O(n \cdot \log(n)) \ll O(n^2)$ steps.

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14. Possibility of parallelization

- For a potentially unlimited number of processors, we:
 - sort the values \underline{x}_i in time $O(\log(n))$;
 - compute the values M_i (solve the prefix-sum problem) in time $O(\log(n))$;
 - find all n values m(i) in parallel $(O(\log(n)))$;
 - check all n inequalities in parallel (time O(1)).
- If we have p < n processors, then we:
 - sort n values in time $O((n \cdot \log(n))/p + \log(n))$;
 - compute M_i in time $O(n/p + \log(p))$;
 - have each processor compute n/p values m(i); time $O((n \cdot \log(n))/p)$;
 - have each processor checks n/p inequalities; time O(n/p).
- Overall time $O\left(\frac{n \cdot \log(n)}{p} + \log(p)\right)$.

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15. Algorithms for constructing lower and upper bounds

- The function f(x) is piecewise constant.
- When x increases, the value of f(x) changes only if when $x = \overline{x}_i$ for some i.
- So, to compute $\underline{f}(x)$, we:
 - sort \overline{x}_i into an increasing sequence:

$$\overline{x}_1 \leq \overline{x}_2 \leq \ldots \leq \overline{x}_n;$$

- compute $m_i \stackrel{\text{def}}{=} \max(y_1, \dots, y_i)$.
- Overall, we need $O(n \cdot \log(n))$ steps to compute f(x).
- Similarly, we need $O(n \cdot \log(n))$ steps to compute $\overline{f}(x)$.
- In parallel, we need time $O(\log(n))$ for p > n processors and $O\left(\frac{n \cdot \log(n)}{p} + \log(p)\right)$ for p < n.

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16. From Monotonicity to More Complex Constraints

- Situation: in some practical problems, we also know that the rate of increase cannot be smaller than a certain value c > 0.
- Question: what are the possible values of dy/dx?
- Mathematical formulation: for a given interval [a, b], for each of such functions f, we take a connected interval hull co(f'([a, b])) of the range of the derivative.
- Then, we consider the intersection F'([a,b]) of these ranges over all such f.
- Result: $F'([a,b]) = \{x : p \le x \le q\}$, where

$$p \stackrel{\mathrm{def}}{=} \min_{i,j: a \leq \overline{x}_i \leq x_j \leq b} \frac{\underline{y}_j - \overline{y}_i}{\underline{x}_j - \overline{x}_i}, \quad q \stackrel{\mathrm{def}}{=} \min_{i,j: a \leq \overline{x}_i \leq x_j \leq b} \frac{\overline{y}_j - \underline{y}_i}{\underline{x}_j - \overline{x}_i}.$$

• These formulas provides a $O(n^2)$ time algorithm for computing the range.



17. Future Work

- Future work: algorithms.
 - Situation: sometimes, we also know the probabilities of different values (x_i, y_i) from the data boxes.
 - Objective: find the probabilities of different stratigraphic maps.
- Future work: applications.
 - Task 1: finalize actual applications of our algorithms to biostratigraphy.
 - $\it Task~2:$ apply to other areas, including areas where fuzzy knowledge is available.

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18. Acknowledgments

- This work was supported:
 - by NASA grant NCC5-209,
 - by USAF grant F49620-00-1-0365,
 - by NSF grants EAR-0112968, EAR-0225670, and EIA-0321328,
 - by Army Research Laboratories grant DATM-05-02-C-0046, and
 - by the NIH grant 3T34GM008048-20S1.
- The authors are thankful:
 - to Luc Longpré (El Paso, Texas),
 - to all the participants of the Geoinformatics meeting at the San Diego Supercomputer Center (August 13–15, 2004), and
 - to the anonymous referees.

