

Trade-Off Between Sample Size and Accuracy: Case of Static Measurements under Interval Uncertainty

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General formulation of...

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A realistic formulation...

Solving the trade-off...

General case (cont-d)

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1. Outline

- In many practical situations, we are not satisfied with the accuracy of the existing measurements.
- There are two possible ways to improve the measurement accuracy:
 - *repeated* measurements;
 - *more accurate* measurements.
- In general, we can combine these two ways:
 - make *repeated* measurements
 - with a *more accurate* measuring instrument.
- What is the appropriate trade-off between sample size and accuracy?
- This is the general problem that we address in this talk.

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2. General formulation of the problem

- Measurements are never 100% accurate, there is always a measurement inaccuracy.
- Manufacturers usually provide the information about the accuracy of the corresponding measurements.
- In many practical situations, we want the result with higher accuracy.
- Two ways to improve the measurement accuracy:
 - make *repeated* measurements (i.e., increase sample size);
 - use a *more accurate* measuring instrument.
- We can also combine these two approaches.
- Problem: finding the best trade-off between sample size and accuracy.

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3. In different practical situations, this general problem can take different forms

- In most practical situations – in *engineering*, *ecology*, etc. – we know what accuracy we want to achieve.
- In *science*, we often face a different objective:
 - we have a certain amount of funding allocated for measuring the value of a certain quantity;
 - we would like to determine the value of the measured quantity as accurately as possible.
- In other words:
 - In engineering situations, we have a fixed accuracy, and we want to minimize the measurement cost.
 - In science, we have a fixed cost, and we want to maximally improve the measurement accuracy.

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4. Trade-off problem: traditional engineering approach

- *Assumptions:*
 - all the measurement errors are normally (Gaussian) distributed known standard deviations σ ;
 - the measurement errors corresponding to different measurement are independent random variables; and
 - the mean value Δ_s of the measurement error is 0.
- *Result:* the average of n measurements has st. dev. $\frac{\sigma}{\sqrt{n}}$.
- *Conclusion:* measurement errors as small as we want.
- *In practice:* the mean (= systematic error) $\Delta_s \neq 0$.
- *Hence:* we underestimate measurement inaccuracy.
- *Example:* $\sigma \approx 0$, $\Delta_s = 0.1$, $x = 1.0$, $\tilde{x} = 1.1$.
- *Conclusion:* averaging does not improve accuracy.

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5. A realistic formulation of the trade-off problem

- *Usually:* we know the upper bound Δ on the systematic error Δ_s : $|\Delta_s| \leq \Delta$.
- *Conclusion:* the largest possible value of the overall error is $\Delta + k_0 \cdot \sigma$, where:
 - 95% confidence corresponds to $k_0 = 2$,
 - 99.9% corresponds to $k_0 = 3$.

- After n measurements, we get $\Delta + k_0 \cdot \frac{\sigma}{\sqrt{n}}$.

- Let $F(\Delta, \sigma)$ denote the cost of a single measurement.

- *Trade-off problem for engineering:*

$$\text{Min. } n \cdot F(\Delta, \sigma) \text{ under the constraint } \Delta + k_0 \cdot \frac{\sigma}{\sqrt{n}} \leq \Delta_0.$$

- *Trade-off problem for science:*

$$\text{Min. } \Delta + k_0 \cdot \frac{\sigma}{\sqrt{n}} \text{ under the constraint } n \cdot F(\Delta, \sigma) \leq F_0.$$

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6. Solving the trade-off problem: general case

- *Discussion:*

- n is a discrete variable;
- discrete optimization is difficult;
- the expressions are approximate anyway;
- so, we treat n as a real-valued variable.

- *Lagrange multiplier method:*

$$n \cdot F(\Delta, \sigma) + \lambda \cdot \left(\Delta + k_0 \cdot \frac{\sigma}{\sqrt{n}} - \Delta_0 \right) \rightarrow \min_{\Delta, \sigma, n}$$

where

$$\Delta + k_0 \cdot \frac{\sigma}{\sqrt{n}} = \Delta_0 \text{ or } n \cdot F(\Delta, \sigma) = F_0.$$

- *Equating derivatives to 0:*

$$n \cdot \frac{\partial F}{\partial \Delta} + \lambda = 0; \quad n \cdot \frac{\partial F}{\partial \sigma} + \lambda \cdot \frac{k_0}{\sqrt{n}} = 0; \quad F - \frac{1}{2} \cdot \lambda \cdot k_0 \cdot \frac{\sigma}{n^{3/2}} = 0.$$

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7. General case (cont-d)

- *Problem:* 4 equations with 4 unknowns λ , n , Δ , and σ .
- *Simplifying:* substituting the expression for λ from the 1st equation, we get the formula

$$n = k_0^2 \cdot \frac{(\partial F / \partial \Delta)^2}{(\partial F / \partial \sigma)^2}.$$

- Substituting this expression for n into remaining equations, we get 2 equations with 2 unknowns Δ and σ :

$$F + \frac{1}{2} \cdot \sigma \cdot \frac{\partial F}{\partial \sigma} = 0;$$
$$\Delta + \frac{\sigma \cdot (\partial F / \partial \sigma)}{\partial F / \partial \Delta} = \Delta_0 \text{ or } k_0^2 \cdot \frac{(\partial F / \partial \Delta)^2}{(\partial F / \partial \sigma)^2} \cdot F = F_0.$$

- After we solve this system, we can use the above expression to find n .
- *Problem:* in practice, we do not have an explicit formula for the measurement cost $F(\Delta, \sigma)$.

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8. How Does the Cost of a Measurement Depend on Its Accuracy?

- *How we can reduce Δ* : by calibrating our measuring instrument against the standard one.

- After N repeated measurements, we conclude that

$$|\Delta_s| \leq k_0 \cdot \sigma / \sqrt{N}.$$

- *Additional problem*: devices deteriorate with time: after time t , we get $\Delta_s(t) = \Delta_s(0) + k \cdot t + o(t)$.
- *Conclusion*: we take $\Delta_s(0) = \Delta/2$, and re-calibrate when $k \cdot t_0 = \Delta/2$, i.e., after $t_0 = \Delta/(2k)$.
- *Assumption*: each calibration costs the same.
- During a fixed time T_0 , we need $T_0/t_0 \sim 1/\Delta$ calibrations, so the cost is $F(\Delta) \sim 1/\Delta$.
- *Empirical analysis*: cost is indeed $\sim 1/\Delta$.

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9. Case of More Accurate Measurements

- *Reminder:* after N repeated measurements, we conclude that $|\Delta_s| \leq k_0 \cdot \sigma / \sqrt{N}$.
- *Conclusion:* to get desired accuracy Δ , we need

$$N \sim \frac{1}{\Delta^2}.$$

- *Reminder:* the necessary number of calibrations is

$$\frac{T_0}{t_0} \sim \frac{1}{\Delta}.$$

- *Conclusion:* the total cost of all $\sim 1/\Delta$ calibrations is

$$F(\Delta) \sim \frac{1}{\Delta^3}.$$

- *General case:* scale invariance leads to $F(\Delta) \approx \text{const}/\Delta^\alpha$ for some constant α .

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10. Trade-off between accuracy and sample size: case of the basic cost model

- *Basic cost model – reminder:* $F(\Delta) = c/\Delta$.

- *Engineering situation – reminder:*

Min. $n \cdot F(\Delta, \sigma)$ under the constraint $\Delta + k_0 \cdot \frac{\sigma}{\sqrt{n}} \leq \Delta_0$.

- *Engineering situation – results:*

$$n_{\text{opt}} = \frac{9 \cdot k_0^2 \cdot \sigma^2}{4 \cdot \Delta_0^2}; \quad \Delta_{\text{opt}} = \frac{1}{3} \cdot \Delta_0.$$

- *Reminder:* the overall error bound Δ_0 is the sum of two error components:

- the systematic error component bounded by Δ , and
- random error component bounded by $k_0 \cdot \frac{\sigma}{\sqrt{n}}$.

- *Observation:* in the optimal trade-off, these error bounds are of approximately the same size.

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11. Case of the basic cost model: cont-d

- *Reminder:* in the optimal trade-off, the systematic and random error components are of \approx the same size.
- *Resulting heuristic:* make sure that all error components are of the same size.
- *Example:* engineering situation under basic cost model.
- *Conclusion:* in this example, the above heuristic is only 20% worse than the optimum.
- *Scientific situation – reminder:*

Min. $\Delta + k_0 \cdot \frac{\sigma}{\sqrt{n}}$ under the constraint $n \cdot F(\Delta, \sigma) \leq F_0$.

- *Scientific situation – result:*

$$n_{\text{opt}} = \left(\frac{F_0 \cdot k_0 \cdot \sigma}{2 \cdot c} \right)^{2/3}; \quad \Delta_{\text{opt}} = \frac{n_{\text{opt}} \cdot c}{F_0}.$$

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12. Cases of more accurate and cutting-edge measurements

- *Cost model – reminder:* $F(\Delta) = c/\Delta^\alpha$.
- Min. $n \cdot F(\Delta, \sigma)$ under the constraint $\Delta + k_0 \cdot \frac{\sigma}{\sqrt{n}} \leq \Delta_0$.
- *Engineering situation – results:*

$$n_{\text{opt}} = \frac{(\alpha + 2)^2 \cdot k_0^2 \cdot \sigma^2}{4 \cdot \Delta_0^2}; \quad \Delta_0 = \frac{\alpha}{2 + \alpha} \cdot \Delta_0.$$

- Min. $\Delta + k_0 \cdot \frac{\sigma}{\sqrt{n}}$ under the constraint $n \cdot F(\Delta, \sigma) \leq F_0$.
- *Scientific situation – results:*

$$n_{\text{opt}} = \left(\frac{F_0}{c}\right)^{2/(2+\alpha)} \cdot \left(\frac{k_0 \cdot \alpha}{2}\right)^{(2\alpha)/(2+\alpha)}; \quad \Delta_{\text{opt}} = \frac{\alpha}{2} \cdot k_0 \cdot \frac{\sigma}{\sqrt{n_{\text{opt}}}}$$

- *Observation:* in both situations, the systematic error component is \approx the random error component.

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13. Acknowledgments

This work was supported in part by:

- by the Japan Advanced Institute of Science and Technology (JAIST) International Joint Research Grant 2006-08,
- by Texas Department of Transportation contract No. 0-5453,
- by National Science Foundation grants HRD-0734825, EAR-0225670, and EIA-0080940, and
- and by the Max Planck Institut für Mathematik.

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