

# Is There a Contradiction Between Statistics and Fairness: From Intelligent Control to Explainable AI

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## 1. Social Applications of AI

- Recent AI techniques like deep learning have led to many successful applications.
- For example, we can apply deep learning to decide:
  - whose loan applications should be approved and whose applications should be rejected,
  - and if approved, what interest should we charge.
- We can apply deep learning to decide:
  - which candidates for graduate program to accept,
  - and for those accepted what financial benefits to offer as an enticement.
- In all such cases, we feed the system with numerous past examples of successes and failures.

## 2. Social Applications of AI (cont-d)

- Based on these example, the systems predict whether a given loan will be a success.
- Statistically, these systems work well: they predict success or failure better than human decision makers.
- However, the results are often not satisfactory. Let us explain why.

### 3. Many Current Social Applications of AI Are Unsatisfactory

- On average, loan applications from poorer geographic areas have a higher default rate.
- This is a known fact, and statistical methods underlying machine learning find this out.
- As a result, the system naturally recommends rejection of all loans from these areas.
- This is not fair to people with good credit record who happen to live in the not-so-good areas.
- Moreover, it is also detrimental to the bank.
- Indeed, the bank will miss on profiting from such potentially successful loans.
- Similarly, in many disciplines women has a lower success rates in getting their PhDs than men.

## 4. Many Current Social Applications of AI Are Unsatisfactory (cont-d)

- Women also, on average, take longer to succeed.
- One of the main reasons for this is that raising children requires much more efforts from women than from men.
- A statistical system, crudely speaking, does not care about the reasons.
- This system just takes this statistical fact into account and preferably selects males.
- Not only this is not fair, this way the universities miss a lot of talent.
- And nowadays, with not much need for routine boring work, talent and creativity are extremely important.
- Talent and creativity should be nurtured, not rejected.

## 5. So Is There a Contradiction Between Statistics And Fairness?

- It seems that if we want the systems to be fair:
  - we cannot rely on statistics only,
  - we need to supplement statistics with additional fairness constraints.
- The need for such constraints is usually formulated as the need for *explainable AI*.
- The main idea behind explainable AI is that:
  - instead of relying on a machine learning system as a black box,
  - we extract some rules from this system,
  - and if these rules are not fair, we replace them with fairer rules.

## 6. What We Show in This Talk

- We show that the seeming inconsistency comes from the fact that we use simplified statistical models.
- We show that:
  - a more detailed description of the corresponding uncertainty – probabilistic or fuzzy,
  - eliminates this seeming contradiction, and
  - enables the system to come up with fair decisions without any need for additional constraints.

## 7. Examples of Unfair Decisions

- We want to understand why the existing techniques can lead to unfair solutions.
- So let us trace some detailed simplified examples.
- We will start with statistical examples.
- Then, we will show that:
  - mathematically similar examples – this time not related to fairness,
  - can be found in applications of fuzzy techniques as well,
  - namely, when we apply the usual intelligent control techniques.



## 8. A Simplified Statistical Example

- Let us consider a statistical version of a classical AI example:
  - birds normally fly,
  - penguins are birds,
  - penguins normally do not fly, and
  - Sam is a penguin.
- The question is: does Sam fly?
- To make it into a statistical example, let us add some probabilities.
- Let us assume:
  - that 90% of the birds fly, and
  - that 99% of the penguins do not fly.

## 9. A Simplified Example (cont-d)

- Of course, in reality, 100% of the penguins do not fly.
- However, let us keep it under 100% since in most real-life situations, we are never 100% sure about anything.
- From the viewpoint of common sense, the information about birds flying in general is rather irrelevant.
- Indeed, we know that Sam is not just any bird, it is a penguin.
- Penguins are very specific type of bird for which we know the probability of flying.
- So, to find the probability of Sam flying, we should only take into account information about penguins.
- Thus, we should conclude that the probability of Sam flying is  $100 - 99 = 1\%$ .

## 10. A Simplified Example (cont-d)

- However, this is not what we would get if we use the standard statistical techniques.
- Indeed, from the purely statistical viewpoint, here we have two rules that lead us to two different conclusions:
  - since Sam is a bird, we can make a conclusion  $A$  that Sam flies, with probability  $a = 90\%$ ; and
  - since Sam is a penguin, we can make a conclusion  $B$  that Sam does not fly, with probability  $b = 99\%$ .
- These two conclusions cannot be both right.
- Indeed, the probabilities of Sam flying and not flying should add up to 1, and here we have

$$0.9 + 0.99 = 1.89 > 1.$$

- This means that these conclusions are inconsistent.

## 11. A Simplified Example (cont-d)

- From the purely logical viewpoint, if we have two statements  $A$  and  $B$ , we can have four possible situations:
  - both  $A$  and  $B$  are true, i.e.,  $A \& B$ ;
  - $A$  is true but  $B$  is false, i.e.,  $A \& \neg B$ ;
  - $A$  is false but  $B$  is true, i.e.,  $\neg A \& B$ ; and
  - both  $A$  and  $B$  are false, i.e.,  $\neg A \& \neg B$ .
- The probabilities  $P(.)$  of all four situations can be obtained by using the Maximum Entropy Principle.
- This is a natural extension of the Laplace Indeterminacy Principle.
- According to Maximum Entropy Principle,
  - if we do not know the dependence between two random variables,
  - then we should assume that they are independent.

## 12. A Simplified Example (cont-d)

- For independent events, probabilities multiply, so  
 $P(A \& B) = P(A) \cdot P(B) = a \cdot b$ ,  $P(A \& \neg B) = a \cdot (1 - b)$ ,  
 $P(\neg A \& B) = (1 - a) \cdot b$ ,  $P(\neg A \& \neg B) = (1 - a) \cdot (1 - b)$ .
- In our case, the statements  $A$  and  $B$  are inconsistent, so we cannot have  $A \& B$  and we cannot have  $\neg A \& \neg B$ .
- The only two consistent options are  $A \& \neg B$  and  $\neg A \& B$ .

- Thus, the true probabilities  $P(A)$  and  $P(B)$  can be found if we restrict ourselves to consistent situations:

$$P(A) = P(A \mid \text{consistent}) = \frac{P(A \& \text{consistent})}{P(\text{consistent})} =$$

$$\frac{P(A \& \neg B)}{P(A \& \neg B) + P(\neg A \& B)} = \frac{a \cdot (1 - b)}{a \cdot (1 - b) + (1 - a) \cdot b}.$$

- In our example, with  $a = 0.9$  and  $b = 0.99$ , we get

$$P(A) = \frac{0.9 \cdot 0.01}{0.9 \cdot 0.01 + 0.1 \cdot 0.99} = \frac{0.009}{0.009 + 0.099} = \frac{1}{12} \approx 8\%.$$

## 13. A Simplified Example (cont-d)

- So, instead the desired 1%, we get a much larger 8% probability.
- This value is clearly affected by the general rule that birds normally fly.
- This is a simplified example.
- However, it explains why recommendation systems based on usual statistical rules becomes biased:
  - if a person with a perfect credit history happens to live in a poor neighborhood,
  - this person's chances of getting a loan will be decreased.

## 14. A Simplified Example (cont-d)

- Similarly:
  - if a female student with perfect credentials applies for a graduate program,
  - the system would be treating her less favorably,
  - since in general, in computer science, female students succeed with lower frequency.
- In both cases, we have clearly unfair situations:
  - the system designers may honestly give female students a better chance to succeed, but
  - instead, their inference system perpetrates the inequality.

## 15. A Simplified Fuzzy Example

- A fuzzy-related reader may view the above example as one more example of:
  - why statistical methods are not always applicable,
  - and why alternative methods – such as fuzzy methods – are needed.
- Alas, we will show that a very similar example is possible if we use the usual fuzzy techniques.
- This problem may not be well known for fuzzy recommendation systems – since there few of them.
- However, it is exactly the same problem that is well known in fuzzy control.
- And fuzzy control is a traditional application area of fuzzy techniques.



## 16. A Simplified Fuzzy Example (cont-d)

- Indeed, suppose that we have two rules that describe how the control  $u$  should depend on the input  $x$ :
  - if  $x$  is small, then  $u$  is small; and
  - if  $x = 0.2$ , then  $u = 0.3$ .
- Suppose also that the notion “small” is described by a triangular membership function

$$\mu_{\text{small}}(x) = \max(1 - |x|, 0).$$

- From the common sense viewpoint, the first rule is more general.
- The second rule describes a specific knowledge that we have about control corresponding to  $x = 0.2$ .
- The second rule is actually in full agreement with the first one.

## 17. A Simplified Fuzzy Example (cont-d)

- Such situations can happen, e.g., when we combine:
  - the general expert knowledge (the first rule) with
  - the results of specific calculations (second rule).
- In this case, for  $x = 0.2$ , we know the exact control value  $u = 0.3$ .
- So, we should return this control value.
- Suppose that we have fuzzy rules “if  $A_i(x)$  then  $B_i(u)$ ”,  $i = 1, \dots, n$ .
- This means that a control  $u$  is reasonable for given value  $x$  if:
  - either the first rule is applicable, i.e.,  $A_1(x)$  is true and  $B_1(u)$  is true,
  - or the second rule is applicable, i.e.,  $A_2(x)$  is true and  $B_2(u)$  is true, etc.

## 18. A Simplified Fuzzy Example (cont-d)

- Let us denote this property “ $u$  is reasonable for  $x$ ” by  $R(x, u)$ .
- In usual notations  $\&$  for “and” and  $\vee$  for “or”, the above text will become the following formula:

$$R(x, u) \leftrightarrow (A_1(x) \& B_1(u)) \vee (A_2(x) \& B_2(u)) \vee \dots$$

- In line with the general fuzzy methodology:
  - for situations in which we are not 100% sure about the properties  $A_i$  and  $B_j$ ,
  - we can apply the corresponding fuzzy versions  $f_{\&}(a, b)$  and  $f_{\vee}(a, b)$  of usual “and” and “or”.
- Then, for the degree  $\mu_r(x, u)$  to which  $u$  is reasonable for  $x$ , we get the following formula:

$$\mu_r(x, u) = f_{\vee}(f_{\&}(\mu_{A_1}(x), \mu_{B_1}(u)), f_{\&}(\mu_{A_2}(x), \mu_{B_2}(u)), \dots).$$

## 19. A Simplified Fuzzy Example (cont-d)

- In particular, for the simplest possible “and”- and “or”-operations  $f_{\&}(a, b) = \min(a, b)$  and  $f_{\vee}(a, b) = \max(a, b)$ :  
$$\mu_r(x, u) = \max(\min(\mu_{A_1}(x), \mu_{B_1}(u)), \min(\mu_{A_2}(x), \mu_{B_2}(u)), \dots).$$
- Once we have this degree for each  $u$ , we can find the control  $\bar{u}$  corresponding to  $x$  by requiring that:
  - its mean square deviation from the actual value  $u$
  - weighted by this degree,
  - is the smallest possible.
- In precise terms, for a given  $x$ , we minimize the expression  $\int \mu_r(x, u) \cdot (u - \bar{u})^2$ .
- Differentiating this expression with respect to  $\bar{u}$  and equating the derivative to 0, we get the formula

$$\bar{u} = \frac{\int \mu_r(x, u) \cdot u \, du}{\int \mu_r(x, u) \, du}.$$

## 20. A Simplified Fuzzy Example (cont-d)

- This formula is known as *centroid defuzzification*.
- Let us apply this technique to our two rules, for the case when  $x = 0.2$  and thus,  $\mu_{\text{small}}(x) = 0.8$ .
- In the second rule, both the condition and the conclusion are crisp:
  - we have  $\mu_{A_2}(0.2) = 1$  and  $\mu_{A_2}(x) = 0$  for all other values  $x$ , and
  - we have  $\mu_{B_2}(0.3) = 1$  and  $\mu_{B_2}(u) = 0$  for all other values  $u$ .
- Thus, for all  $u \neq 0.2$ , we have  $\mu_r(x, u) = \min(\mu_{\text{small}}(u), 0.8)$  and for  $u = 0.2$ , we have  $\mu_r(x, u) = 1$ .
- According to the centroid formula, the resulting control is the above ratio of two integrals.

## 21. A Simplified Fuzzy Example (cont-d)

- The single-point change in the function  $\mu_r(x, u)$  does not affect its integral.
- So the numerator is simply equal to the integral of the product

$$\min(\mu_{\text{small}}(u), 0.8) \cdot u = \min(\max(1 - |u|), 0), 0.8) \cdot u.$$

- This product is an odd function of  $u$ :
  - the first factor does not change if we replace  $u$  with  $-u$ , and
  - the second factor changes sign.
- Thus, its integral is 0.
- So, the usual fuzzy methodology leads to  $u = 0$ .
- However, from the viewpoint of common sense, we should get  $u = 0.3$ .

## 22. General Description of the Problem

- In all previous example, we considered the case of situations when we have two rules.
- For example, in the case of loans:
  - the first rule is that loans recipients from poor areas often default on a loan, and
  - the second rule is that people with a good credit record usually pay back their loans.
- From the common sense viewpoint:
  - for a person with a good credit record living in a poor area,
  - we should go with the second rule.
- However, the naive statistical approach pays an unnecessarily high attention to the first rule as well.

## 23. General Description of the Problem (cont-d)

- And this approach underlies in current machine learning systems.
- Similarly, for Sam the penguin:
  - we have a general rule applicable to all the birds – that they usually fly; and
  - we have a second specific rule, applicable only to penguins – that they do not fly.
- From the common sense viewpoint, since Sam is a penguin, we should go with the second rule.
- However, the naive statistical approach gives too much weight to the first rule.

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## 24. How Can We Distinguish Between a More General And a More Specific Rule?

- One important difference is that a more specific case describes a sub-sample.
- In this sub-sample, all the objects are, in some reasonable sense, similar.
- Thus, they differ from each other less than in the general sample.
- So, for many quantities, the standard deviation  $\sigma$  is much larger in the larger sample.
- This is simple and reasonable, and – as we show:
  - it helps put more weight on a more general rule and,
  - thus, it helps avoid the contradiction between statistics and fairness.

## 25. How to Combine Statistical Rules With Different Means And Standard Deviations

- To illustrate our point, let us consider the simplest situation when we have two statistical rules.
- Let's assume that these rules come from two independent sets of arguments or observation.
- Both rules predict the value of a quantity  $x$ , and we are absolutely confident in both of these rules.
- Since these are statistical rules:
  - they do not predict the exact value of the quantity,
  - they only predict the probabilities of different possible values of this quantity.
- These probabilities can be described by the corresponding probability density functions  $\rho_1(x)$  and  $\rho_2(x)$ .

## 26. How to Combine Statistical Rules (cont-d)

- If these were rules predicting two different quantities  $x_1$  and  $x_2$ , then:
  - due to the fact that these rules are assumed to be independent,
  - the probability to have values  $x_1$  and  $x_2$  should be equal to the product  $\rho_1(x_1) \cdot \rho_2(x_2)$ .
- However, in our case, we know that these distributions describe the exact same quantity, i.e., that  $x_1 = x_2$ ; so:
  - instead of the above 2-D probability density,
  - we need to consider the *conditional* probability density, under the condition that  $x_1 = x_2$ .
- It is known that for  $A \subseteq B$ ,  $P(A | B) = \frac{P(A)}{P(B)}$ .
- So,  $P(A | B) = c \cdot P(A)$  for some constant  $c$ .

## 27. How to Combine Statistical Rules (cont-d)

- Thus, in our case, the resulting probability density is equal to  $\rho(x) = c \cdot \rho_1(x) \cdot \rho_2(x)$ , where  $c$  is a constant.
- This constant can be determined from the condition  $\int \rho(x) dx = 1$ , so  $\rho(x) = \frac{\rho_1(x) \cdot \rho_2(x)}{\int \rho_1(y) \cdot \rho_2(y) dy}$ .
- Often, both probability distributions  $\rho_1(x)$  and  $\rho_2(x)$  are Gaussian:  $\rho_i(x) = \text{const} \exp\left(-\frac{(x - a_i)^2}{2\sigma_i^2}\right)$ .
- Here,  $a_i$  are means and  $\sigma_i$  are standard deviations.
- Then, as one can easily check, the resulting distribution is also Gaussian, with

$$a = \frac{a_1 \cdot \sigma_1^{-2} + a_2 \cdot \sigma_2^{-2}}{\sigma_1^{-2} + \sigma_2^{-2}} \text{ and } \sigma^{-2} = \sigma_1^{-2} + \sigma_2^{-2}.$$

## 28. How Is This Applicable to Our Examples

- Let us consider the case of a loan. Here, we have two pieces of information about a loan applicant:
  - the first piece of information is that this person has a good credit history;
  - the second piece of information is that this person lives in a poor area.
- To combine these two pieces of information, let us estimate the corresponding means and st. dev.
- Let us start with the estimates corresponding to people with good credit history.
- In most cases, people with good credit history return their loans – and return them on time.
- So, the mean value  $a_1$  of the returned percentage of the loan  $x$  is close to 100.

## 29. Application to Our Examples (cont-d)

- The corresponding standard deviation is  $\sigma_1$  is close to 0.
- On the other hand, in general, for people living in a poor area, the returned percentages vary:
  - some people living in the poor area struggle, but return their loans,
  - some fail and become unable to return their loans.
- Here, the average  $a_2$  is clearly less than 100, and the standard deviation  $\sigma_2$  is clearly much larger than  $\sigma_1$ :

$$\sigma_2 \gg \sigma_1.$$

- If we multiply both the numerator and the denominator of the formula for  $a$  by  $\sigma_1^2$ , we get:

$$a = \frac{a_1 + a_2 \cdot (\sigma_1^2/\sigma_2^2)}{1 + \sigma_1^2/\sigma_2^2}.$$

## 30. Application to Our Examples (cont-d)

- Since here  $\sigma_1 \ll \sigma_2$ , we get  $a \approx a_1$ .
- So, we conclude that:
  - the resulting estimate is fully determined by the fact that the applicant has a good credit history;
  - this estimate is practically *not* affected by the fact that the applicant happens to live in a poor area.
- This is exactly what we wanted the system to conclude.
- Similar arguments help resolve the bird-fly puzzle.
- As a measure of a flying ability, we can take, e.g., the time that a bird can stay in the air.
- No penguin can really fly.
- So for penguins, this time is always small, and the standard deviation of this time is close to 0:  $\sigma_1 \approx 0$ .

## 31. Application to Our Examples (cont-d)

- On the other hand, if we consider the population of all the birds, then there is a large variance:
  - some birds can barely fly for a few minutes, while
  - others can fly for days and cross the oceans.
- For this piece of knowledge, the variance is huge and thus, the standard deviation  $\sigma_2$  is also huge.
- Here too,  $\sigma_1 \ll \sigma_2$ .
- Thus, our conclusion about Sam's ability to fly:
  - will be determined practically exclusively by the fact that Sam is a penguin,
  - in full agreement with common sense.



## 32. How Is This Idea Applicable to Fuzzy

- The main difference between a probability density function  $\rho(x)$  and a membership function  $\mu(x)$  is that:
  - for a probability density function,  $\int \rho(x) dx = 1$ ;
  - for a membership function,  $\max_x \mu(x) = 1$ .
- As a result:
  - if we have a probability density function  $\rho(x)$ , then we can normalize it as membership function:

$$\mu(x) = \frac{\rho(x)}{\max_y \rho(y)};$$

- if we have a membership function  $\mu(x)$ , then we can normalize it as a probability density function:

$$\rho(x) = \frac{\mu(x)}{\int \mu(y) dy}.$$

### 33. Let Us Use This Relation to Combine Fuzzy Knowledge

- We know how to combine probabilistic knowledge.
- So, if we have two membership functions  $\mu_1(x)$  and  $\mu_2(x)$ , we can combine them as follows.
- First, we transform the membership functions into probability density functions  $\rho_i(x) = c_i \cdot \mu_i(x)$ , for some constants  $c_i$ .
- Second, we combine  $\rho_1(x)$  and  $\rho_2(x)$  into a single probability density function  $\rho(x) = \text{const} \cdot \rho_1(x) \cdot \rho_2(x)$ .
- Due to the above relation between probability and fuzzy, we get  $\rho(x) = c_3 \cdot \mu_1(x) \cdot \mu_2(x)$  for some constant  $c_3$ .
- Finally, we transform the resulting probability function  $\rho(x)$  back into a membership function:

$$\mu(x) = c_4 \cdot \rho(x) = c \cdot \mu_1(x) \cdot \mu_2(x).$$

## 34. This Idea Allows Us to Avoid the Problem of Traditional Defuzzification

- Let us show that this combination rule enables us to avoid the problem of traditional defuzzification.
- Indeed, suppose that we have two rules:
  - one rule corresponding to a very narrow membership function (i.e., in prob. terms, very small  $\sigma$ ),
  - and another rule with a very wide membership function (i.e., with large  $\sigma$ ).
- Then, as we have mentioned, in the combined function:
  - the contribution of the wide rule will be largely ignored, and
  - the conclusion will be practically identical with what the narrow rule recommends – exactly as we want.

### 35. What If We Are Only Partly Confident About Some Piece of Knowledge?

- The above combination formula describes how to combine two rules about which we are fully confident.
- But what if we have some rules about which we are only partly confident?
- One way to interpret degree of confidence in a statement is:
  - to have a poll of  $N$  experts and,
  - if  $M$  out of  $N$  experts confirm this statement, to take  $M/N$  as the degree of confidence.
- Let us describe the membership function when only one expert confirms the statement by  $\mu_1(x)$ .

## 36. Partial Confidence (cont-d)

- In this case, according to the above combination formula:
  - the case when  $M$  experts confirm the statement
  - is described by a membership function proportional to  $\mu_1^M(x)$ .
- In particular, the case of full confidence, when all  $N$  experts confirm the statement, we have  $\mu(x) \sim \mu_1^N(x)$ .
- Thus,  $\mu_1(x) \sim (\mu(x))^{1/N}$ .
- So, the membership function  $\sim \mu_1^M(x)$  corr. to degree of confidence  $d = M/N$  is  $\sim (\mu(x))^{M/N} = \mu^d(x)$ .
- In general:
  - if we have a rule like  $A(x) \rightarrow B(u)$ ,
  - then for each input  $x$ , our degree of confidence in the conclusion  $B(u)$  is equal to  $d = \mu_A(x)$ .

## 37. Partial Confidence (cont-d)

- Thus, the resulting membership function about  $u$  should be proportional to  $(\mu_B(u))^{\mu_A(x)}$ .
- Usually, we have several rules

$$A_1(x) \rightarrow B_1(u), \quad A_2(x) \rightarrow B_2(u), \dots$$

- Then we can take the product:

$$(\mu_{B_1}(u))^{\mu_{A_1}(x)} \cdot (\mu_{B_2}(u))^{\mu_{A_2}(x)} \cdot \dots$$

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