

# Equations Without Equations: Challenges on a Way to a More Adequate Formalization of Reasoning in Physics

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*Need to Formalize...*

*Mathematician's View...*

*Physicists' Explanation*

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# 1. Need to Formalize Reasoning in Physics

- *Fact*: in medicine, geophysics, etc., expert systems use automated expert reasoning to help the users.
- *Hope*: similar systems may be helpful in general theoretical physics as well.
- *What is needed*: describe physicists' reasoning in precise terms.
- *Reason*: formalize this reasoning inside an automated computer system.
- *Formalized part of physicists' reasoning*: theories are formulated in terms of PDEs (or ODEs)  $\frac{dx}{dt} = F(x)$ .
- *Meaning*: these equations describe how the corresponding fields (or quantities)  $x$  change with time  $t$ .

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## 2. Mathematician's View of Physics and Its Limitations

- *Mathematician's view*: we know the initial conditions  $x(t_0)$  at some moment of time  $t_0$ .
- We solve the corresponding Cauchy problem and find the values  $x(t)$  for all  $t$ .
- *Limitation*: not all solutions to the equation  $\frac{dx}{dt} = F(x)$  are physically meaningful.
- *Example 1*: when a cup breaks into pieces, the corresponding trajectories of molecules make physical sense.
- *Example 2*: when we reverse all the velocities, we get pieces assembling themselves into a cup.
- *Fact*: this is physically impossible.
- *Fact*: the reverse process satisfies all the original (T-invariant) equations.

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### 3. Physicists' Explanation

- *Reminder*: not all solutions to the physical equation are physically meaningful.
- *Explanation*: the “time-reversed” solution is non-physical because its initial conditions are “degenerate”.
- *Clarification*: once we modify the initial conditions even slightly, the pieces will no longer get together.
- *Conclusion*: not only the equations must be satisfied, but also the initial conditions must be “non-degenerate”.
- *Two challenges* in formalizing this idea:
  - how to formalize “non-degenerate”;
  - the separation between equations and initial conditions depends on the way equations are presented.
- *First challenge*: can be resolved by using Kolmogorov complexity and randomness.

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## 4. First Example: Schrödinger's Equation

- *Example:* Schrödinger's equation

$$i\hbar \cdot \frac{\partial \Psi}{\partial t} = -\frac{\hbar^2}{2m} \cdot \nabla^2 \Psi + V(\vec{r}) \cdot \Psi.$$

- *In this representation:* the potential  $V$  is a part of the equation, and  $\Psi(\vec{r}, t_0)$  are initial conditions.
- *Transformation:*
  - we represent  $V(\vec{r})$  as a function of  $\Psi$  and its derivatives,
  - differentiate the right-hand side by time, and
  - equate the derivative w.r.t. time to 0.
- *Result:*

$$\frac{\partial}{\partial t} \left( \frac{i\hbar}{\Psi} \cdot \frac{\partial \Psi}{\partial t} + \frac{\hbar^2}{2m} \cdot \frac{\nabla^2 \Psi}{\Psi} \right) = 0.$$

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## 5. First Example (cont-d)

- *Reminder:*

$$\frac{\partial}{\partial t} \left( \frac{i\hbar}{\Psi} \cdot \frac{\partial \Psi}{\partial t} + \frac{\hbar^2}{2m} \cdot \frac{\nabla^2 \Psi}{\Psi} \right) = 0.$$

- *Mathematically:* the new equation (2nd order in time) is equivalent to the Schrödinger's equation:
  - every solution of the Schrödinger's equation for any  $V(\vec{r})$  satisfies this new equation, and
  - every solution of the new equation satisfies Schrödinger's equation for some  $V(\vec{r})$ .
- *Observation:* in the new equation, initial conditions, in effect, include  $V(\vec{r})$ .
- *Conclusion:* “non-degeneracy” (“randomness”) condition must now include  $V(\vec{r})$  as well.

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## 6. Second Example: General Scalar Field

- *Example:* consider a scalar field  $\varphi$  with a generic Lagrange function  $L(\varphi, a)$ , with  $a \stackrel{\text{def}}{=} \varphi_{,i}\varphi^{,i}$ .
- *Traditional formulation:* every Lagrangian is possible, but initial conditions  $\varphi(x, t_0)$  must be non-degenerate.

- *Euler equations:*  $\frac{\partial L}{\partial \varphi} - \partial_i \frac{\partial L}{\partial \varphi_{,i}} = L_{,\varphi} - \partial_i (2L_{,a} \cdot \varphi_{,i}) = 0:$

$$L_{,\varphi} - 2L_{,a} \cdot \square \varphi - 2L_{,a\varphi} \cdot (\varphi_{,i}\varphi^{,i}) - 4L_{,aa} \cdot \varphi_{,ij}\varphi^{,i}\varphi^{,j} = 0.$$

- In general, on a 3-D Cauchy surface  $t = t_0$ , we can find points with arbitrary combination of  $(\varphi, \varphi_{,i}\varphi^{,i}, \square \varphi)$ .
- Thus, by observing the evolution, we can find  $\varphi_{,ij}\varphi^{,i}\varphi^{,j}$  for all possible triples  $(\varphi, \varphi_{,i}\varphi^{,i}, \square \varphi)$ .
- So, we can predict future evolution – w/o knowing  $L$ .

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## 7. Scalar Field: Discussion and Conclusions

- *Observation*: the new “equation” does not contain  $L$  at all.
- *Fact*: a field  $\varphi$  satisfies the new equation  $\Leftrightarrow$  it satisfies the Euler-Lagrange equations for *some*  $L$ .
- *Observation*:
  - similarly to Wheeler’s cosmological “mass without mass” and “charge without charge”,
  - we now have “equations without equations”.
- *Conclusion*: when formalizing physical equations:
  - we must not only describe them in *a* mathematical form,
  - we must also select *one* of the mathematically equivalent forms.

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