

Economics of Engineering Design under Interval (and Fuzzy) Uncertainty: Case Study of Building Design

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1. Formulation of the Problem

- *General problem of engineering design:*
 - *given:* constraints (requirements);
 - *find:* the cheapest design among all that satisfy given constraints.
- *Checking constraints is often difficult:*
 - *Example:* a building must be stable under all possible distribution of loads in different rooms.
 - *Problem:* checking all distribution is not possible.
- *Mathematical description of the problem:*
 - *we know:*
 - * *constraints* $f(x_1, \dots, x_n) \leq f_0$,
 - * *ranges* $\mathbf{x}_i = [\underline{x}_i, \bar{x}_i]$ of x_i .
 - *check:* whether $f(x_1, \dots, x_n) \leq f_0$ for all $x_i \in \mathbf{x}_i$.

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2. Existing Techniques for Solving The Problem: Idea

- *Check:* $f(x_1, \dots, x_n) \leq f_0$ for all $x_i \in [\tilde{x}_i - \Delta_i, \tilde{x}_i + \Delta_i]$.
- *Natural approach:* compute the range
$$\mathbf{y} = [\underline{y}, \bar{y}] = \{f(x_1, \dots, x_n) \mid x_1 \in \mathbf{x}_1, \dots, x_n \in \mathbf{x}_n\},$$
and check whether $\bar{y} \leq f_0$.
- *Idea:* ranges are usually narrow.
- *So:* terms quadratic in $\Delta x_i \stackrel{\text{def}}{=} x_i - \tilde{x}_i$ can be ignored:
$$\Delta y = c_1 \cdot \Delta x_1 + \dots + c_n \cdot \Delta x_n, \text{ where } c_i \stackrel{\text{def}}{=} \frac{\partial f}{\partial x_i}.$$
- *Analysis:*
 - the sum is max when each term is max;
 - when $c_i > 0$, the i -th term is max when $\Delta x_i = \Delta_i$;
 - when $c_i < 0$, the i -th term is max when $\Delta x_i = -\Delta_i$.
- *Resulting formula:* $\Delta = |c_1| \cdot \Delta_1 + \dots + |c_n| \cdot \Delta_n$.

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3. Existing Techniques for Solving The Problem: Algorithms

- *Reminder:* given $f(x_1, \dots, x_n)$, and values \tilde{x}_i and Δ_i , compute $\Delta = |c_1| \cdot \Delta_1 + \dots + |c_n| \cdot \Delta_n$, where $c_i \stackrel{\text{def}}{=} \frac{\partial f}{\partial x_i}$.
- *Case of explicit f :* differentiate and compute Δ .
- *Case when we know a code computing f (in time T):*
 - *method:* Automatic Differentiation (AD);
 - *result:* we compute c_1, \dots, c_n in time $\leq 3T$.
- *Case of proprietary software:*
 - *situation:* we are only allow to use f as a black box;
 - *solution:* numerical differentiation
$$c_i = \frac{f(\tilde{x}_1, \dots, \tilde{x}_{i-1}, \tilde{x}_i + h_i, \tilde{x}_{i+1}, \dots, \tilde{x}_n) - \tilde{y}}{h_i}$$
 - *problem:* takes too much time $n \cdot T \gg T$.

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4. Towards Simulation Techniques: Need, Problems

- *For probabilistic setting:* Monte-Carlo simulation speeds up computations.
- *Objective:* design similar fast technique for the interval setting.
- *Problem:*
 - *probabilistic case:* we know the exact distribution;
 - *interval case:* we may have different distributions.
- *Possible solutions and their limitations:*
 - *use one distribution:* no guarantee that the results will be valid for other distributions;
 - *use many distributions:*
 - * takes a lot of time, and
 - * still no guarantee.

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5. New Algorithm: Idea

- *Cauchy distribution*: density $\rho(z) = \frac{\Delta}{\pi \cdot (z^2 + \Delta^2)}$.
- *Useful property*:
 - if z_1, \dots, z_n are independent Cauchy distributed with parameters Δ_i ,
 - then $z = c_1 \cdot z_1 + \dots + c_n \cdot z_n$ is also Cauchy distributed, with $\Delta = |c_1| \cdot \Delta_1 + \dots + |c_n| \cdot \Delta_n$.
- *Resulting idea*:
 - simulate δ_i Cauchy distributed with parameters Δ_i ;
 - then

$$c = f(\tilde{x}_1 + \delta_1, \dots, \tilde{x}_n + \delta_n) - f(\tilde{x}_1, \dots, \tilde{x}_n) = c_1 \cdot \delta_1 + \dots + c_n \cdot \delta_n$$

is Cauchy distributed with the desired parameter Δ .

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6. Towards an Algorithm: Technical Details

- *How to simulate Cauchy distribution:*

- computers generate random r_i uniform on $[0,1]$;
- we can then compute $\delta_i = \Delta_i \cdot \tan(\pi \cdot (r_i - 0.5))$.

- *How to estimate Δ :*

- *Idea:* Maximum Likelihood Method

$$\rho(c^{(1)}) \cdot \rho(c^{(2)}) \cdot \dots \cdot \rho(c^{(N)}) \rightarrow \max.$$

- *Resulting equation:*

$$\frac{1}{1 + \left(\frac{c^{(1)}}{\Delta}\right)^2} + \dots + \frac{1}{1 + \left(\frac{c^{(N)}}{\Delta}\right)^2} = \frac{N}{2}.$$

- *Property:* l.h.s. is \uparrow in Δ , going from $0 (< N/2)$ for $\Delta = 0$ to $> N/2$ for $\Delta = \max |c^{(k)}|$.

- *Algorithm:* apply bisection to the interval $[0, \max |c^{(k)}|]$.

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7. Resulting Algorithm

- Compute $\tilde{y} := f(\tilde{x}_1, \dots, \tilde{x}_n)$.
- For $k = 1, 2, \dots, N$, repeat the following:
 - use the standard random number generator to compute $r_i^{(k)}$, $i = 1, 2, \dots, n$;
 - compute Cauchy distributed values

$$c_i^{(k)} := \tan(\pi \cdot (r_i^{(k)} - 0.5));$$

- compute $K := \max_i |c_i^{(k)}|$;
- compute the simulated errors $\delta_i^{(k)} := \Delta_i \cdot c_i^{(k)} / K$;
- compute the simulated values $x_i^{(k)} := \tilde{x}_i + \delta_i^{(k)}$;
- compute $c^{(k)} := K \cdot \left(f \left(x_1^{(k)}, \dots, x_n^{(k)} \right) - \tilde{y} \right)$.

- Use bisection for $\sum_{k=1}^n \frac{1}{1 + \left(\frac{c^{(k)}}{\Delta} \right)^2} = \frac{N}{2}$, compute Δ .

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8. When Is This Randomized Algorithm Better than Deterministic Numerical Differentiation?

- *We used:* maximum likelihood method (ML).
- *Known:* the error of ML is (asymptotically) normal, with 0 average and st. dev. $\sim 1/\sqrt{N} \cdot I$, where:

$$I = \int_{-\infty}^{\infty} \frac{1}{\rho} \cdot \left(\frac{\partial \rho}{\partial \Delta} \right)^2 dz.$$

- *For Cauchy distribution:* $\sigma_e \sim \Delta \cdot \sqrt{2/N}$.
- *Two sigma bound:* with probability 95%, the estimate Δ differs from its actual by $\leq 2\sigma_e = 2\Delta \cdot \sqrt{2/N}$.
- *Example:* for 20% accuracy in Δ , take $N = 200$.
- *Conclusion:* select
 - a deterministic algorithm when $n \leq N_0 \approx 200$;
 - a randomized algorithm if $n \geq N_0$.

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- *If we can only use $N_0 < 200$ simulations:*
 - we still get an approximate value of the range Δ ;
 - the accuracy can be computed as above.
- *Parallelization:*
 - *idea:* run all N simulations in parallel;
 - *advantage:* speed up the computations.
- *What if intervals are not narrow:*
 - *we assumed:* intervals \mathbf{x}_i are narrow;
 - *in practice:* some ranges may be wide;
 - *solution:*
 - * bisect $[\underline{x}_i, \bar{x}_i]$ into narrower subintervals;
 - * estimate the range over each subinterval;
 - * take the union.

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10. Conclusions

- *Practical problem:* check whether $f(x_1, \dots, x_n) \leq f_0$ for all possible values of parameters $x_i \in [\underline{x}_i, \bar{x}_i]$.
- *Solution:*
 - compute the range $[\underline{y}, \bar{y}]$ of f , and
 - check $\bar{y} \leq f_0$.
- *When we know the code for f :* use automatic differentiation (AD) and compute the range in time $O(T + n)$.
- *For proprietary f :* numerical differentiation requires time $T \cdot n \gg T + n$.
- *New method:* computes the range in time $O(T)$.
- *Main idea:* use (artificial) Monte-Carlo simulations with Cauchy distribution.

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