

# Why Superellipsoids: A Probability-Based Explanation

Pedro Barragan Olague  
and Vladik Kreinovich

Department of Computer Science  
University of Texas at El Paso  
El Paso, TX 79968, USA  
pabarraganolague@miners.utep.edu  
vladik@utep.edu

[Outline](#)[Need to Describe...](#)[Shall Not We Also...](#)[Empirical Shapes of...](#)[First Idea:...](#)[Second Idea: Scale...](#)[Definitions and the...](#)[Discussion](#)[Proof](#)[Home Page](#)[Title Page](#)[«](#)[»](#)[◀](#)[▶](#)[Page 1 of 17](#)[Go Back](#)[Full Screen](#)[Close](#)[Quit](#)

## 1. Outline

- In many practical situations, possible values of the deviation vector form (approximately) a super-ellipsoid.
- In this talk, we provide a theoretical explanation for this empirical fact.
- This explanation is based on the natural notion of scale-invariance.

## 2. Need to Describe Uncertainty Domains

- The intent of mass production is to produce gadgets with same values  $(x_1, \dots, x_n)$  of the characteristics  $x_i$ .
- In reality, different gadgets have slightly different values  $\tilde{x}_i$  of these characteristics:  $\Delta x_i \stackrel{\text{def}}{=} \tilde{x}_i - x_i \neq 0$ .
- For each of these characteristics  $x_i$ , we usually have a tolerance bound  $\Delta_i$  for which  $|\Delta x_i| \leq \Delta_i$ .
- Possible values of  $\Delta x_i$  form an interval  $[-\Delta_i, \Delta_i]$ .
- Thus, possible values of the deviation vector  $\Delta x = (\Delta x_1, \dots, \Delta x_n)$  are in the box

$$[-\Delta_1, \Delta_1] \times \dots \times [-\Delta_n, \Delta_n].$$

- In practice, not all  $\Delta x$  from this box are possible.
- It is desirable to describe the set  $S$  of all possible deviation vectors  $\Delta x$ ;  $S$  is called *uncertainty domain*.

Need to Describe...

Shall Not We Also...

Empirical Shapes of...

First Idea:...

Second Idea: Scale...

Definitions and the...

Discussion

Proof

Home Page

Title Page

◀

▶

◀

▶

Page 3 of 17

Go Back

Full Screen

Close

Quit

### 3. Shall Not We Also Determine Probabilities?

- At first glance, it seems that we should be interested:
  - not only in finding out which deviation vectors  $\Delta x$  are possible and which are not,
  - but also in how frequent different possible vectors are.
- In other words, we should be interested in the probability distribution on this domain.
- In reality, however, it is not possible to find these probabilities.
- Indeed, the manufacturing process may slightly change (and often does change).
- After each such change, the tolerance intervals and the uncertainty domain remain largely unchanged.
- However, the probabilities change (often drastically).

## 4. Empirical Shapes of Uncertainty Domains

- In many practical cases, the uncertainty domain can be well approximated by a *super-ellipsoid*:

$$\sum_{i=1}^n \left( \frac{|\Delta x_i|}{\sigma_i} \right)^p \leq C.$$

- Their approximation accuracy is higher than for other families with the same number of parameters.
- Super-ellipsoids are also actively used in image processing, to describe different components of an image.
- In this talk, we provide a theoretical explanation for this empirical phenomenon.

## 5. First Idea: Probabilistic Approach

- In reality, there *is* some probability distribution  $\rho_i(\Delta x_i)$  for each of the random variables  $\Delta x_i$ .
- We have no reason to assume that positive or negative values of  $\Delta x_i$  are more probable.
- So, it makes sense to assume that they are equally probable.
- So, each distribution  $\rho_i(\Delta x_i)$  is symmetric:  $\rho_i(\Delta x_i) = \rho_i(|\Delta x_i|)$ .
- Similarly, we have no reasons to believe that different deviations are statistically dependent.
- So, it makes sense to assume that random variables  $\Delta x_i$  are independent:  $\rho(\Delta x) = \prod_{i=1}^n \rho_i(|\Delta x_i|)$ .
- Usually, we consider a deviation vector possible if its probability exceed some  $t$ :  $S_t \stackrel{\text{def}}{=} \{\Delta x : \rho(\Delta x) \geq t\}$ .

## 6. Second Idea: Scale Invariance

- Numerical values of the deviations  $\Delta x_i$  depend on the choice of a measuring unit.
- If we replace the original unit by a  $\lambda$  times smaller one, we get new numerical values  $\Delta x'_i = \lambda \cdot \Delta x_i$ .
- Since the physics remains the same, it makes sense to require that the uncertainty domains do not change.
- To be more precise, the pdf threshold  $t$  may change, but the family of such sets should remain unchanged.
- So, we require that  $\{S'_t\}_t = \{S_t\}_t$ , where  $S'_t$  corresponds to the re-scaled pdf  $\rho'(\Delta x) = \text{const} \cdot \rho(\lambda \cdot \Delta)$ .
- We will prove that under this scale-invariance, the corresponding sets  $S_t$  are exactly super-ellipsoids.
- Thus, we will get the desired explanation.

## 7. Definitions and the Main Result

- Let  $n > 1$ , and let  $\rho(y) = (\rho_1(y_1), \dots, \rho_n(y_n))$  be a tuple of positive symmetric smooth functions.
- For every  $t > 0$ , let us denote

$$S_t(\rho) \stackrel{\text{def}}{=} \left\{ (y_1, \dots, y_n) : \prod_{i=1}^n \rho_i(y_i) \geq t \right\}.$$

- We say that a tuple  $\rho(y)$  is *bounded* if the set  $S_t(\rho)$  is bounded for every  $t$ .
- For every  $\lambda > 0$ , by a  $\lambda$ -re-scaling of the tuple  $\rho(x)$ , we mean a tuple  $\rho_\lambda(y)$ , for which  $\rho_{\lambda,i}(y_i) \stackrel{\text{def}}{=} \frac{1}{\lambda} \cdot \rho_i(\lambda \cdot y_i)$ .
- We say that  $\rho(y)$  is *scale-invariant* if for every  $\lambda > 0$ , re-scaling does not change  $\{S_t\}_t$ :  $\{S_t(\rho)\}_t = \{S_t(\rho_\lambda)\}_t$ .
- **Main Result.** *If the tuple  $\rho(y)$  is bounded and scale-invariant, then each set  $S_t(\rho)$  is a super-ellipsoid.*



## 8. Discussion

- Vice versa, it is easy to prove that:
  - each super-ellipsoid

$$\left\{ y : \sum_{i=1}^n \left( \frac{|y_i|}{\sigma_i} \right)^p \leq C \right\}$$

- can be represented as a set  $S_t$  for some bounded and scale-invariant distributions.
- Namely, we can take  $\rho_i(y_i) = \text{const} \cdot \exp\left(-\frac{|y_i|^p}{\sigma_i^p}\right)$ .
- Such probability distributions indeed occur: e.g., as probability distributions of measuring errors.

## 9. Proof

- For convenience, let us consider logarithms

$$\psi_i(y_i) \stackrel{\text{def}}{=} -\log(\rho_i(y_i)).$$

- Let us take the negative logarithm of both sides of the inequality  $\prod_{i=1}^n \rho_i(y_i) \geq t$  that describes the set  $S_t(\rho)$ .

- We then get an equivalent description  $\sum_{i=1}^n \psi_i(y_i) \leq c$ , where we denoted  $c \stackrel{\text{def}}{=} -\log(t)$ .

- In these terms, scale-invariance means that the corresponding family of sets is the same for all  $c$ .

- In terms of the new functions  $\psi_i(y_i)$ , scaling means

$$\begin{aligned}\psi_{\lambda,i}(y_i) &= -\ln(\rho_{\lambda,i}(y_i)) = -\log\left(\frac{1}{\lambda} \cdot \rho_i(\lambda \cdot y_i)\right) = \\ &= \log(\lambda) - \log(\rho_i(\lambda \cdot y_i)) = \psi_i(\lambda \cdot y_i) + \log(\lambda).\end{aligned}$$

## 10. Proof (cont-d)

- So, scaling has the form  $\psi_{\lambda,i}(y_i) = \psi_i(\lambda \cdot y_i) + \log(\lambda)$ .
- In these terms, the fact that scaling does not change the family of sets  $S_t$  implies that
  - if two tuples  $(y_1, \dots, y_n)$  and  $(z_1, \dots, z_n)$  always belong or not belong to the same sets  $S_t$ ,
  - i.e., if  $\sum_{i=1}^n \psi_i(y_i) = \sum_{i=1}^n \psi_i(z_i)$ ,
  - then the re-scaled functions should also have the same value of the sum:  $\sum_{i=1}^n \psi_{\lambda,i}(y_i) = \sum_{i=1}^n \psi_{\lambda,i}(z_i)$ .
- Substituting  $\psi_{\lambda,i}(y_i)$  into this formula, we get

$$\sum_{i=1}^n (\psi_i(\lambda \cdot y_i) + \log(\lambda)) = \sum_{i=1}^n (\psi_i(\lambda \cdot z_i) + \log(\lambda)), \text{ hence}$$

$$\sum_{i=1}^n \psi_i(\lambda \cdot y_i) = \sum_{i=1}^n \psi_i(\lambda \cdot z_i).$$

## 11. Proof (cont-d)

- Thus, we have the following property:

- if  $\sum_{i=1}^n \psi_i(y_i) = \sum_{i=1}^n \psi_i(z_i)$ ,
- then  $\sum_{i=1}^n \psi_i(\lambda \cdot y_i) = \sum_{i=1}^n \psi_i(\lambda \cdot z_i)$ .

- In particular, this property holds if we perform very small changes to only two  $y_i$ 's:

$$y_a \rightarrow z_a = y_a + \delta_a, \quad y_b \rightarrow z_b = y_b + \delta_b.$$

- Here,  $\psi_a(y_a + \delta_a) = \psi_a(y_a) + \psi'_a(y_a) \cdot \delta_a + o(\delta)$ .
- Similarly,  $\psi_b(y_b + \delta_b) = \psi_b(y_b) + \psi'_b(y_b) \cdot \delta_b + o(\delta)$ .
- Thus,  $\sum_{i=1}^n \psi_i(z_i) = \sum_{i=1}^n \psi_i(y_i) + \psi'_a(y_a) \cdot \delta_a + \psi'_b(y_b) \cdot \delta_b + o(\delta)$ .
- So, the original equality  $\sum_{i=1}^n \psi_i(y_i) = \sum_{i=1}^n \psi_i(z_i)$  takes the form  $\psi'_a(y_a) \cdot \delta_a + \psi'_b(y_b) \cdot \delta_b + o(\delta) = 0$ .

## 12. Proof (cont-d)

- Similarly, the equality  $\sum_{i=1}^n \psi_i(\lambda \cdot y_i) = \sum_{i=1}^n \psi_i(\lambda \cdot z_i)$  takes the form  $\psi'_a(\lambda \cdot y_a) \cdot \delta_a + \psi'_b(\lambda \cdot y_b) \cdot \delta_b + o(\delta) = 0$ .
- So, the scale-invariance condition takes the form:
  - if  $\psi'_a(y_a) \cdot \delta_a + \psi'_b(y_b) \cdot \delta_b + o(\delta) = 0$ ,
  - then  $\psi'_a(\lambda \cdot y_a) \cdot \delta_a + \psi'_b(\lambda \cdot y_b) \cdot \delta_b + o(\delta) = 0$ .
- The 1st condition  $\Leftrightarrow -\frac{\delta_b}{\delta_a} = \frac{\psi'_a(y_a)}{\psi'_b(y_b)} + o(\delta)$ .
- The 2nd condition  $\Leftrightarrow -\frac{\delta_b}{\delta_a} = \frac{\psi'_a(\lambda \cdot y_a)}{\psi'_b(\lambda \cdot y_b)} + o(\delta)$ .
- So,  $\frac{\psi'_a(\lambda \cdot y_a)}{\psi'_b(\lambda \cdot y_b)} = \frac{\psi'_a(y_a)}{\psi'_b(y_b)} \Rightarrow \frac{\psi'_a(\lambda \cdot y_a)}{\psi'_a(y_a)} = \frac{\psi'_b(\lambda \cdot y_b)}{\psi'_b(y_b)}$ .
- The left-hand side of this equality doesn't depend on  $y_b$ ; thus, the right-hand side doesn't depend on  $y_b$ .

### 13. Proof (cont-d)

- Hence, this ratio depends only on  $\lambda$ . Let us denote this common ratio by  $r(\lambda)$ :  $\psi'_a(\lambda \cdot y_a) = r(\lambda) \cdot \psi'_a(y_a)$ .
- The derivative of a smooth function is always measurable.
- Thus, the function  $r(\lambda)$  is also measurable, as a ratio of two measurable functions.
- Now, let us take arbitrary values  $\lambda_1 > 0$  and  $\lambda_2 > 0$ .
- Then, we can re-scale first by  $\lambda_1$ , then by  $\lambda_2$ , or we can right away re-scale by  $\lambda = \lambda_1 \cdot \lambda_2$ .
- In the first case,
$$\psi'(\lambda_1 \cdot \lambda_2 \cdot y_a) = r(\lambda_1) \cdot \psi'(\lambda_2 \cdot y_a) = r(\lambda_1) \cdot r(\lambda_2) \cdot \psi'_a(y_a).$$
- In the 2nd case,  $\psi'(\lambda_1 \cdot \lambda_2 \cdot y_a) = r(\lambda_1 \lambda_2) \cdot \psi'_a(y_a)$ .
- So, we must have  $r(\lambda_1 \cdot \lambda_2) = r(\lambda_1) \cdot r(\lambda_2)$ .

## 14. Proof (cont-d)

- It is known that all measurable functions satisfying this property have the form  $r(\lambda) = \lambda^\beta$  for some  $\beta$ .
- So,  $\psi'_a(\lambda \cdot y_a) = r(\lambda) \cdot \psi'_a(y_a) = \lambda^\beta \cdot \psi'_a(y_a)$ .
- For  $\lambda = z$  and  $y_a = 1$ , we get  $\psi'_a(z) = \psi'_a(1) \cdot z^\beta$ , i.e., that  $\psi'_a(y_a) = c_a \cdot y_a^\beta$  for some  $c_a$ .
- Integrating, for  $\beta \neq -1$ , for  $y_a > 0$ , we get  $\psi_a(y_a) = k_a \cdot y_a^p + C_a$  for  $p = \beta + 1$ ,  $k_a \stackrel{\text{def}}{=} \frac{c_a}{\beta + 1}$ .
- Since  $\psi_i(y_i)$  is even, we get  $\psi_i(y_i) = k_i \cdot |y_i|^p + C_i$ .
- So, the condition  $\sum_{i=1}^n \psi(y_i) \leq c$  takes the super-ellipsoid form  $\sum_{i=1}^n k_i \cdot |y_i|^p \leq c_0 \stackrel{\text{def}}{=} c - \sum_{i=1}^n C_i$ .
- For this super-ellipsoid to be bounded, we need to have  $p > 0$ .

## 15. Proof (final)

- To complete the proof, it is sufficient to consider the case when  $\beta = -1$ .
- For  $\beta = -1$ , integration leads to

$$\psi_i(y_i) = k_i \cdot \ln(|y_i|) + C_i.$$

- So the condition  $\sum_{i=1}^n \psi_i(y_i) \leq c$  takes the form

$$\sum_{i=1}^n k_i \cdot \ln(|y_i|) \leq c_0 \stackrel{\text{def}}{=} c - \sum_{i=1}^n C_i.$$

- Exponentiating both sides, we get  $\prod_{i=1}^n |y_i|^{k_i} \leq \exp(C)$ , for which the corresponding set  $S_t$  is unbounded.
- So, in the bounded cases, we always have a super-ellipsoid. The result is proven.



## 16. Acknowledgments

This work was supported in part:

- by the National Science Foundation grants:
  - HRD-0734825 and HRD-1242122  
(Cyber-ShARE Center of Excellence) and
  - DUE-0926721, and
- by an award from Prudential Foundation.

[Outline](#)[Need to Describe...](#)[Shall Not We Also...](#)[Empirical Shapes of...](#)[First Idea:...](#)[Second Idea: Scale...](#)[Definitions and the...](#)[Discussion](#)[Proof](#)[Home Page](#)[Title Page](#)[Page 17 of 17](#)[Go Back](#)[Full Screen](#)[Close](#)[Quit](#)