How to Describe Correlation in the Interval Case?

Carlos Jimenez, Francisco Zapata, and Vladik Kreinovich

University of Texas at El Paso, El Paso, TX 79968, USA cjimenez23@miners.utep.edu, fazg74@gmail.com, vladik@utep.edu



1. Correlations Are Ubiquitous

- One of the main objectives of science and engineering is to improve the world,
 - to enhance good things and
 - to make sure that bad things do not happen.
- The state of the world is usually described by the values of different quantities.
- In these terms, our objective is to change the values of the corresponding quantities:
 - to increase the economy's growth rate,
 - to decrease unemployment,
 - to decrease the patient's body temperature or blood pressure, etc.
- In many practical situations, we cannot change these quantities directly.



2. Correlations Are Ubiquitous (cont-d)

- Thus, the only way to change them is to change them *indirectly*: i.e.,
 - to find auxiliary possible-to-change quantities that are *correlated* with the desired ones
 - in the sense that changes in these auxiliary quantities will lead to the desired changes in the quantities of interest.
- For example:
 - a change in the central bank's interest rate or a change in tax rules can boost the economy,
 - a change in the patient's diet and/or exercise schedule can lower his/her blood pressure, etc.
- In some cases, we know which two quantities are correlated.



3. Correlations Are Ubiquitous (cont-d)

- In many other situations, we are actively looking for quantities which are correlated with the desired ones.
- For example:
 - for many diseases,
 - we are actively looking for ways to control the genes that would help fight these diseases.
- Looking for correlations is important.
- It is therefore important to have an adequate description of this intuitive notion.



4. What Is Correlation: Main Idea

- The main idea: the use of x can improve our ability to predict y.
- In other words, correlation means that
 - if we take x into account,
 - then we can get more accurate predictions of y than if we don't.
- Similarly, the absence of correlation means that the use of x cannot help in predicting y.
- For example, intuitively, fluctuations of a quasar's flux are not related to weather.
- This means that:
 - even if we add quasar's flux as a possible additional variable into the weather prediction models,
 - we will not get more accurate predictions.

What Is Correlation: . . . Need for Linear Models How to Gauge... Resulting Formula for . . . Need to Go Beyond . . . How to Gauge Model . . Relation to Interval... Resulting Definition of . . Home Page Title Page **>>** Page 5 of 23 Go Back Full Screen Close Quit

Correlations Are . . .

5. What Is Correlation (cont-d)

- To describe this idea in precise terms, we need to formally describe:
 - what models we consider and
 - how we measure model's accuracy.



6. Need for Linear Models

- When we do not consider x at all, then the only possible models for y are models in which y = const.
- When we take x into account, we thus get models of the type y = f(x), for some function f(x).
- Which functions should we consider?
- \bullet In most cases, changes in both x and y are small.
- We are happy when the growth rate increases from 2% to 3%.
- We are happy when the upper blood pressure falls from 140 to 130, etc.



7. Need for Linear Models (cont-d)

- When changes in x are small, i.e., when all the values x have the form $x_0 + \Delta x$ for some small Δx , then:
 - we can expand the dependence $f(x) = f(x_0 + \Delta x)$ on Δx and
 - ignore terms which are quadratic or of higher order in terms of Δx .
- In this case, we get a linear model $f(x) = a_0 + a_1 \cdot \Delta x$.
- Substituting $\Delta x = x x_0$ into this expression, we conclude that

$$f(x) = a_0 + a_1 \cdot (x - x_0) = (a_0 - a_1 \cdot x_0) + a_1 \cdot x.$$

• Thus, it makes sense to restrict ourselves to linear models.



8. How to Gauge Accuracy: Traditional Approach

- Models are practically always approximate.
- It is very rare to have a model that enables us to predict the exact value of a quantity.
- Many independent reasons cause model's predictions $f(x_i)$ to be different from the actual values y_i .
- Thus, the difference $\Delta y_i = y_i f(x_i)$ is the sum of many independent random variables.
- Most of these variables are of about the same size.



9. How to Gauge Accuracy (cont-d)

- In probability theory, there is a result known as *Central Limit Theorem* according to which,
 - when the number of components is large,
 - the distribution of the sum of many small independent components is close to Gaussian (normal).
- The larger the number of such components, the closer we are to a Gaussian distribution.
- In practice, we usually have many different reasons causing the model to differ from reality.
- So, we can safely assume that the difference Δy_i is normally distributed.
- A normal distribution for Δy can be characterized by its mean μ and its standard deviation σ .



10. How to Gauge Accuracy (cont-d)

- Different reasons cause lead to positive and negative differences; so, it is reasonable to assume that:
 - on average, such reasons cancel each other and
 - the mean values of the difference is 0.
- So, the only parameter that describes the model's accuracy is the standard deviation σ .
- Factors influencing different measurements are, in general, independent.
- Thus, the differences Δy_i corresponding to different measurements i are independent.
- Since the mean is 0, the square σ^2 of the standard deviation i.e., the variance can be estimated as

$$\sigma^2 \approx \frac{1}{n} \cdot \sum_{i=1}^n (\Delta y_i)^2.$$



11. How to Gauge Accuracy (cont-d)

- \bullet Here n denotes the overall number of measurements.
- We want to find the most accurate model, i.e., the model for which σ is as small as possible.
- Minimizing σ is equivalent to minimizing σ^2 , which, in its turn, is equivalent to minimizing the sum $\sum_{i=1}^{n} (\Delta y_i)^2$.
- Here, we are minimizing the sum of the squares (of differences).
- So, this method of finding the most adequate model is known as the *Least Squares Method*.



12. Resulting Formula for Correlation

- If we do not take x into account, then the only models we have are the models y = const.
- To find the best such model, we find the constant for which the corresponding variance is the smallest:

$$\sigma_y^2 = \min_a \left(\frac{1}{n} \cdot \sum_{i=1}^n (y_i - a)^2 \right).$$

- If we take x into account, then we allow models of the type $y \approx a + b \cdot x$.
- Then, for the best such model, we get the variance

$$\sigma_{y|x}^2 = \min_{a,b} \left(\frac{1}{n} \cdot \sum_{i=1}^n (y_i - (a+b \cdot x_i))^2 \right).$$

• If x and y are not correlated, then the use of x will lead to more accurate models for y: $\sigma_{y|x}^2 = \sigma_y^2$.



13. Resulting Formula for Correlation (cont-d)

- On the other hand, if y is uniquely determined by x, i.e., if $y = a + b \cdot x$, then $\sigma_{y|x}^2 = 0 \ll \sigma_y^2$.
- In general, intuitively, the larger part of original variance is decreased by using x, the larger the correlation.
- So, it's reasonable to define correlation as

$$C_{y|x} = 1 - \frac{\sigma_{y|x}^2}{\sigma_y^2}.$$

• This intuitive idea is well described by the usual statistical correlation: $C_{y|x} = \rho_{xy}^2$, where

$$\rho_{xy} = \frac{C_{xy}}{\sigma_x \cdot \sigma_y}, \quad C_{xy} \stackrel{\text{def}}{=} \frac{1}{n} \cdot \sum_{i=1}^n (x_i - \overline{x}) \cdot (y_i - \overline{y}),$$

$$\overline{x} \stackrel{\text{def}}{=} \frac{1}{n} \cdot x_i, \ \overline{y} \stackrel{\text{def}}{=} \frac{1}{n} \cdot y_i, \ \sigma_x^2 \stackrel{\text{def}}{=} \frac{1}{n} \cdot (x_i - \overline{x})^2, \text{ and } \sigma_y^2 \stackrel{\text{def}}{=} \frac{1}{n} \cdot (y_i - \overline{y})^2.$$

Correlations Are...

What Is Correlation:...

Need for Linear Models

How to Gauge...

Resulting Formula for...

Need to Go Beyond...

How to Gauge Model...

Relation to Interval...

Resulting Definition of . . .

Home Page

Title Page





Page 14 of 23

Go Back

Full Screen

Close

Quit

14. Need to Go Beyond Normal Distributions

- We assumed that many independent factors are of approximately the same size.
- Then the differences $\Delta y = y f(x)$ are normally distributed.
- In practice, however, there may be a few major reasons for the difference.
- In this case, the quantity Δy is not necessarily normally distributed.
- In this case, what is the reasonable formalization of the intuitive notion of correlation?



15. How to Gauge Model Accuracy

- We do not know the probability distribution of the model inaccuracy Δy .
- So, a natural idea is to consider the absolute values of this inaccuracy; namely:
 - if for one model, we always have $|\Delta y| \leq \Delta_1$,
 - and for another model, we always have $|\Delta y| \leq \Delta_2$ with $\Delta_2 < \Delta_1$,
 - then the second model is more accurate than the first one.
- As a measure of model's accuracy, it is therefore reasonable to take the smallest Δ for which $|\Delta y| \leq \Delta$:

$$\Delta = \max_{i} |\Delta y_i| = \max_{i} |y_i - f(x_i)|.$$



16. Relation to Interval Uncertainty

- For all x, we have $|\Delta y| = |y f(x)| \le \Delta$.
- This means that for each x, the value y belongs to the interval $[f(x) \Delta, f(x) + \Delta]$.
- Thus, the above case corresponds to interval uncertainty.

What Is Correlation: . . . Need for Linear Models How to Gauge . . . Resulting Formula for . . . Need to Go Beyond . . . How to Gauge Model . . Relation to Interval... Resulting Definition of . . Home Page Title Page **>>** Page 17 of 23 Go Back Full Screen Close Quit

Correlations Are . . .

17. Resulting Definition of Correlation

- If we do not use x, then the only possible models are constant models y = b.
- The accuracy of the best such model can be described by the quantity $\Delta_y = \min_a \left(\max_i |y_i a| \right)$.
- One can easily check that the corresponding value a is equal to $a = \frac{1}{2} \cdot \left(\min_{i} y_i + \max_{i} y_i \right)$.
- The corresponding value $\Delta_y = \frac{1}{2} \cdot \left(\max_i y_i \min_i y_i \right)$.
- If we allow x, then the best accuracy of the corresponding linear models $y \approx a + b \cdot x$ is

$$\Delta_{y|x} = \min_{a,b} \left(\max_{i} |y_i - (a + b \cdot x_i)| \right).$$

• Similarly to the usual case, it is therefore reasonable to define correlation as $\rho_{y|x}^{\text{int}} = 1 - \frac{\Delta_{y|x}}{\Delta_{x}}$.



18. Open Question

• The usual statistical correlation is symmetric:

$$\rho_{xy} = \rho_{yx}.$$

• Is the interval analogue of correlation symmetric?



19. Case of Non-Linear Dependence

- The actual dependence is sometimes non-linear.
- It is thus reasonable to also include, e.g., quadratic (or even cubic) terms in the corresponding model.
- Then we consider, e.g., the values

$$\sigma_{y|x}^2 = \min_{a,b,c} \left(\frac{1}{n} \cdot \sum_{i=1}^n \left| y_i - \left(a + b \cdot x_i + c \cdot x_i^2 \right) \right|^2 \right) \text{ or }$$

$$\Delta_{y|x} = \min_{a,b,c} \left(\max_{i} \left| y_i - \left(a + b \cdot x_i + c \cdot x_i^2 \right) \right| \right).$$

• In addition to such quadratic etc. polynomials, we can also consider other families of models.



Dependence on Several Variables

• We can consider dependence on different quantities

$$x_1, \dots, x_k, \text{ e.g., as } C_{y|x_1, \dots, x_k}^{\text{int}} = 1 - \frac{\sigma_{y|x_1, \dots, x_k}^2}{\sigma_y^2}, \text{ with } \sigma_{y|x_1, \dots, x_k}^2 \stackrel{\text{def}}{=}$$

$$\min_{a,b_1,...,b_k} \left(\frac{1}{n} \cdot \sum_{i} |y_i - (a + b_1 \cdot x_{1i} + ... + b_k \cdot x_{ki})|^2 \right).$$

• We can also take $C_{y|x_1,...,x_k}^{\text{int}} = 1 - \frac{\Delta_{y|x_1,...,x_k}}{\Delta_{x_k}}$, where

$$\Delta_{y|x_1,\dots,x_k} = \min_{a,b_1,\dots,b_k} \left(\max_i |y_i - (a + b_1 \cdot x_{1i} + \dots + b_k \cdot x_{ki})| \right)$$

Correlations Are . . . What Is Correlation: . .

Need for Linear Models

How to Gauge . . .

Resulting Formula for . . .

Need to Go Beyond . . .

How to Gauge Model . .

Relation to Interval... Resulting Definition of . .

Title Page

Home Page















Quit

21. Robust Techniques

- We can also consider cases of *robust statistics* when we do not know the probability distribution.
- It is known as *robust* statistics.
- An example are ℓ^p -methods in which the model's accuracy is described by a value s for which

$$s^p = \frac{1}{n} \cdot \sum_{i=1}^n |\Delta y_i|^p.$$

• Then, we can define $C_{p,y|x} = 1 - \frac{s_{y|x}^p}{s_y^p}$, where

$$s_y^p = \min_a \left(\frac{1}{n} \cdot \sum_{i=1}^n |y_i - a|^p \right)$$
 and

$$s_{y|x}^p = \min_{a,b} \left(\frac{1}{n} \cdot \sum_{i=1}^n |y_i - (a+b \cdot x_i)|^p \right).$$

What Is Correlation: . . . Need for Linear Models How to Gauge . . . Resulting Formula for . . . Need to Go Beyond . . . How to Gauge Model . . Relation to Interval... Resulting Definition of . . Home Page Title Page **>>** Page 22 of 23 Go Back Full Screen Close Quit

Correlations Are . . .

22. Acknowledgments

This work was supported in part by the National Science Foundation grant HRD-1242122 (Cyber-ShARE Center).

Correlations Are... What Is Correlation: . . . Need for Linear Models How to Gauge . . . Resulting Formula for . . Need to Go Beyond . . . How to Gauge Model . . . Relation to Interval . . . Resulting Definition of. Home Page Title Page 44 Page 23 of 23 Go Back Full Screen Close

Quit