

# Experimental Determination of Mechanical Properties Is, In General, NP-Hard – Unless We Measure Everything

Yan Wang<sup>1</sup>, Oscar Galindo<sup>2</sup>, Michael Baca<sup>2</sup>,  
Jake Lasley<sup>2</sup>, and Vladik Kreinovich<sup>2</sup>

<sup>1</sup>School of Mechanical Engineering, Georgia Institute of Technology,  
Atlanta, GA 30332-0405, USA, [yan.wang@me.gatech.edu](mailto:yan.wang@me.gatech.edu)

<sup>1</sup>University of Texas at El Paso, El Paso, TX 79968, USA  
[ogalindomo@miners.utep.edu](mailto:ogalindomo@miners.utep.edu), [mvbaca@miners.utep.edu](mailto:mvbaca@miners.utep.edu)  
[jlasley@miners.utep.edu](mailto:jlasley@miners.utep.edu), [vladik@utep.edu](mailto:vladik@utep.edu)

Linear Elasticity: a...

Ideal Case

In Practice, We Only...

How Complex: What...

Definition

Main Result

Proof

First Series of...

Second Series of...

Home Page

Title Page

◀

▶

◀

▶

Page 1 of 17

Go Back

Full Screen

Close

Quit

## 1. Linear Elasticity: a Brief Reminder

- A force applied to a rubber band extends it or curves it.
- In general, a force applied to different parts of an elastic body changes the mutual location of its points.
- Once we know the forces applied at different locations, we can determine the deformations.
- Vice versa, we can determine the forces once we know all the deformations.
- In general, the dependence on forces  $f_\alpha$  at different locations  $\alpha$  on different displacement  $\varepsilon_\beta$  is non-linear.
- However, usually, displacements are small.
- We can ignore terms quadratic or higher order in terms of  $\varepsilon_\beta$ .

[Ideal Case](#)[In Practice, We Only ...](#)[How Complex: What ...](#)[Definition](#)[Main Result](#)[Proof](#)[First Series of ...](#)[Second Series of ...](#)[Home Page](#)[Title Page](#)[<<](#)[>>](#)[<](#)[>](#)[Page 2 of 17](#)[Go Back](#)[Full Screen](#)[Close](#)[Quit](#)

## 2. Linear Elasticity (cont-d)

- Thus, we can safely assume that the dependence of each component  $f_\alpha$  on  $\varepsilon_\beta$  is linear.
- Taking into account that in the absence of forces, there is no displacement, we conclude that  $f_\alpha = \sum_{\beta} K_{\alpha,\beta} \cdot \varepsilon_\beta$ .
- The coefficients  $K_{\alpha,\beta}$  describe the mechanical properties of the body.
- It is therefore desirable to experimentally determine these coefficients.

### 3. Ideal Case

- In the ideal case, we measure displacements  $\varepsilon_\beta$  and forces  $f_\alpha$  at all possible locations.
- Each measurement results in an equation which is linear in terms of the unknowns  $K_{\alpha,\beta}$ :

$$f_\alpha = \sum_{\beta} K_{\alpha,\beta} \cdot \varepsilon_\beta$$

- Thus, after performing sufficiently many measurements, we get an easy-to-solve system of linear equations.
- Solving this system enables us to find the values  $K_{\alpha,\beta}$ .

## 4. In Practice, We Only Measure Some Values

- In reality, we only measure displacements and forces at some locations.
- So, we know only some values  $f_\alpha$  and  $\varepsilon_\beta$ .
- Since both  $K_{\alpha,\beta}$  and some  $\varepsilon_\beta$  are unknown, the corresponding system of equations becomes quadratic.
- After sufficiently many measurements, we may still uniquely determine  $K_{\alpha,\beta}$ .
- However, the reconstruction is more complex.

## 5. How Complex: What We Prove

- How complex is the corresponding computational problem?
- In this talk, we prove that the corresponding reconstruction problem is, in general, NP-hard.
- This means that, if – as most computer scientists believe –  $\text{NP} \neq \text{P}$ ,
  - no feasible algorithm is possible
  - that would always reconstruct the mechanical properties  $K_{\alpha,\beta}$  based on the experimental results.
- We will prove NP-hardness even for the following:
  - given  $\alpha_0$ ,  $\beta_0$ , and  $K_0$ ,
  - check whether for some solution,  $K_{\alpha_0,\beta_0} = K_0$ .

## 6. Definition

- From the computational viewpoint, the above problem can be formulated as follows.
- Let  $N$  be a natural number. This number will be called *the number of experiments*.
- By a *problem of experimentally determining mechanical properties*, we mean the following problem.
  - We know that for every  $n$  from 1 to  $N$ , we have  $f_\alpha^{(n)} = \sum_{\beta} K_{\alpha,\beta} \cdot \varepsilon_\beta^{(n)}$  for some values  $f_\alpha^{(n)}$  and  $\varepsilon_\beta^{(n)}$ .
  - For each  $n$ , we know some of the values  $f_\alpha^{(n)}$  and  $\varepsilon_\beta^{(n)}$ .
  - We need to check if for given  $\alpha_0$ ,  $\beta_0$ , and  $K_0$ , we can have  $K_{\alpha_0,\beta_0} = K_0$ .

## 7. Main Result

**Proposition.** *The problem of experimentally determining mechanical properties is NP-hard.*

Linear Elasticity: a . . .

Ideal Case

In Practice, We Only . . .

How Complex: What . . .

Definition

Main Result

Proof

First Series of . . .

Second Series of . . .

Home Page

Title Page



Page 8 of 17

Go Back

Full Screen

Close

Quit



## 8. Proof

- By definition, NP-hard means that all the problems from a certain class NP can be reduced to this problem.
- It is known that the following *subset sum* problem is NP-hard:
  - given  $m + 1$  natural numbers  $s_1, \dots, s_m, S$ ,
  - check whether it is possible to find the values  $x_i \in \{0, 1\}$  for which

$$\sum_{i=1}^m s_i \cdot x_i = S.$$

- We check whether there is a subset of the values  $s_1, \dots, s_m$  whose sum is equal to the given value  $S$ .
- The subset sum problem is NP-hard.
- This means that every problem from the class NP can be reduced to subset sum.

## 9. Proof (cont-d)

- So, if we reduce the subset problem to our problem, that would mean, by transitivity of reduction, that
  - every problem from the class NP
  - can be reduced to our problem as well.
- So, our problem is indeed NP-hard.
- Let  $s_1, \dots, s_m, S$  be the values that describe an instance of the subset sum problem.
- Let us reduce it to the following instance of our problem.
- In this instance, we have  $2m + 1$  variables

$$\varepsilon_0, \varepsilon_1, \dots, \varepsilon_m, \varepsilon_{m+1}, \dots, \varepsilon_{2m}.$$

- We also have  $m + 1$  different values  $f_\alpha, \alpha = 0, 1, \dots, m$ .

## 10. First Series of Experiments

- For each  $i = 1, \dots, m$ , we have  $\varepsilon_i^{(i)} = 1$ ,  $\varepsilon_{m+i}^{(i)} = -1$ , and  $\varepsilon_j^{(i)} = 0$  for all  $j \neq i$ .
- The only value of  $f_\alpha$  that we measure in each of these experiments is the value  $f_0^{(i)} = 0$ ; then

$$0 = f_0^{(i)} = \sum_{\beta} K_{0,\beta} \cdot \varepsilon_{\beta}^{(i)} = K_{0,i} - K_{0,m+i}.$$

- We conclude that  $K_{0,m+i} = K_{0,i}$ .

## 11. Second Series of Experiments

- For each  $n = m+i$ , we measure  $\varepsilon_j^{(m+i)} = 0$  for all  $j \neq n$ , and we measure  $f_0^{(m+i)} = f_i^{(m+i)} = 1$ .
- From the corresponding equations, we conclude that  $1 = K_{0,m+i} \cdot \varepsilon_{m+i}^{(m+i)}$  and  $1 = K_{i,m+i} \cdot \varepsilon_{m+i}^{(m+i)}$ .
- We do not know the value  $\varepsilon_{m+i}^{(m+i)}$ .
- However, we can find it from the first equation and substitute into the second one.
- As a result, we conclude that  $K_{0,m+i} = K_{i,m+i}$ .
- We know that  $K_{0,i} = K_{0,m+i}$ , thus  $K_{0,i} = K_{i,m+i}$ .

## 12. Third Series of Experiments

- For each  $i$ , we measure  $\varepsilon_i^{(2m+i)} = 1$ ,  $\varepsilon_j^{(2m+i)} = 0$  for all other  $j$ , and we measure  $f_i^{(2m+i)} = 1$ .
- The corresponding equation implies that  $K_{i,i} = 1$ .

### 13. Fourth Series of Experiments

- We measure the values  $\varepsilon_{m+i}^{(3m+i)} = -1$  and  $\varepsilon_j^{(3m+i)} = 0$  for all  $j \neq i, m+i$ .
- We also measure the values  $f_0^{(3m+i)} = f_i^{(3m+i)} = 0$ .
- In this case, we get  $K_{0,i} \cdot \varepsilon_i^{(3m+i)} - K_{0,m+i} = 0$  and  $K_{i,i} \cdot \varepsilon_i^{(3m+i)} - K_{i,m+i} = 0$ .
- Since  $K_{i,i} = 1$ , we have  $\varepsilon_i^{(3m+i)} = K_{i,m+i}$ .
- Since  $K_{i,m+i} = K_{0,i}$ , this implies  $\varepsilon_i^{(3m+i)} = K_{0,i}$ .
- Let's substitute this expression for  $\varepsilon_i^{(3m+i)}$  into

$$K_{0,i} \cdot \varepsilon_i^{(3m+i)} - K_{0,m+i} = 0.$$

- Taking into account that  $K_{0,m+i} = K_{0,i}$ , we get

$$K_{0,i}^2 - K_{0,i} = 0.$$

- Thus, for each  $i$  from 1 to  $m$ , we have  $K_{0,i} \in \{0, 1\}$ .

## 14. Final (Fifth) Series: A Single Experiment

- We measure  $\varepsilon_0^{(4m+1)} = -S$ ,  $\varepsilon_1^{(4m+1)} = s_1, \dots, \varepsilon_m^{(4m+1)} = s_m$ , and  $\varepsilon_{m+i}^{(4m+1)} = 0$  for all  $i = 1, \dots, m$ .
- We also measure  $f_0^{(4m+1)} = 0$ .
- We want to check whether it is possible that  $K_{0,0} = 1$ .
- For  $K_{0,0} = 1$ , the corresponding equation takes the form  $-S + K_{0,1} \cdot s_1 + \dots + K_{0,m} \cdot s_m = 0$ .
- So,  $K_{0,1} \cdot s_1 + \dots + K_{0,m} \cdot s_m = S$  for some  $K_{0,i} \in \{0, 1\}$ .
- Suppose that the original instance of the subset sum problem has a solution  $x_i \in \{0, 1\}$ .
- Then the above equality holds for  $K_{0,i} = x_i$ .

## 15. Final Series (cont-d)

- Vice versa, suppose that there exist values  $K_{0,i} \in \{0, 1\}$  that satisfy the formula

$$K_{0,1} \cdot s_1 + \dots + K_{0,m} \cdot s_m = S.$$

- Then the values  $x_i = K_{0,i}$  solve the original subset sum problem:

$$\sum_{i=1}^m s_i \cdot x_i = S.$$

- Thus, we indeed have a reduction – and hence, our problem is indeed NP-hard.



## 16. Acknowledgments

This work was supported in part by the US National Science Foundation grant HRD-1242122 (Cyber-ShARE).

*Linear Elasticity: a ...*

*Ideal Case*

*In Practice, We Only ...*

*How Complex: What ...*

*Definition*

*Main Result*

*Proof*

*First Series of ...*

*Second Series of ...*

*Home Page*

*Title Page*



*Page 17 of 17*

*Go Back*

*Full Screen*

*Close*

*Quit*